Phase Transition in the Number Partitioning Problem

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The Number Partitioning Problem (NPP)

Algorithms for NPP

Phase Transition in NPP

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Outline

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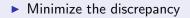
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Number Partitioning Problem (NPP)

- ▶ Input: a list a_1, a_2, \ldots, a_N of positive integers
- ▶ Partition: a subset $A \subset \{1, ..., N\}$
- Discrepancy of partition A:

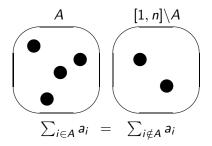
$$E(A) = \left| \sum_{i \in A} a_i - \sum_{i \notin A} a_i \right|$$



NPP: Example

Multi-processor scheduling:

- 2 processors
- ▶ 5 tasks with runtimes 8, 7, 6, 5, 4
- How to divide the jobs among the processors so that the tasks are completed as fast as possible?

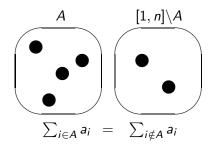


NPP: Example

Multi-processor scheduling:

- 2 processors
- ▶ 5 tasks with runtimes 8, 7, 6, 5, 4
- How to divide the jobs among the processors so that the tasks are completed as fast as possible?
 - Processor 1 runs tasks with runtimes: 8,7
 - Processor 2 runs tasks with runtimes: 6,5,4
 - Discrepancy:

$$|8+7-6-5-4|=0$$

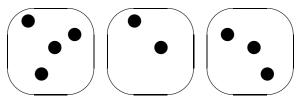


Perfect Partitions

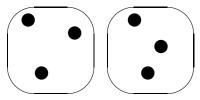
- Perfect partition:
 - Discrepancy E(A) = 0 if $\sum a_i$ even
 - Discrepancy E(A) = 1 if $\sum a_i$ odd
- ► The list 1, 2, 3, 4, 5, 6 has a perfect partition A = {2, 3, 5} because E(A) = |2 + 3 + 5 1 4 6| = 1.
- Not all lists have perfect partitions.

Variations of NPP

- ▶ Input can be a list of real numbers from the interval [0,1]
- Multiway NPP: Partitioning to more than 2 sets



Balanced NPP: The sets must have the same cardinality



Properties of NPP

NP-complete

- Poor quality of heuristic algorithms
 - Average discrepancy of optimum partitions $O(\sqrt{N} \cdot 2^{-N})$ (for real-valued NPP)
 - ► Best heuristic algorithm yields average discrepancies O(N^{-α log N}) (for real-valued NPP)
- The phase transition can be analyzed rigorously analytically. (S. Mertens: Phase Transition in the Number Partition Problem, Phys. Rev. Lett. 81, 4281 (1998))

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The Greedy Algorithm

- Assign the largest unassigned number to the set with the smallest sum
- Iterate until all numbers are assigned
- Keeps the discrepancy small with every decision
- Yields average discrepancies O(1/N) (for real-valued NPP) (S. Mertens: The Easiest Hard Problem: Number Partitioning, in: A.G. Percus, G. Istrate, C. Moore, eds., Computational Complexity and Statistical Physics, Oxford University Press (2006), p. 125-139)
- ► Time complexity $O(N \log N)$ (sorting)

Input: $\{8, 7, 6, 5, 4\}$

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Input: $\{8, 7, 6, 5, 4\}$

lter 1: 8 assigned to set 1
 {8}{}

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- Input: $\{8, 7, 6, 5, 4\}$
- Iter 1: 8 assigned to set 1 $\{8\}\{\}$ Iter 2: 7 assigned to set 2 $\{8\}\{7\}$

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- Input: $\{8, 7, 6, 5, 4\}$
- Iter 1: 8 assigned to set 1 $\{8\}\{\}$ Iter 2: 7 assigned to set 2 $\{8\}\{7\}$
 - Iter 3: 6 assigned to set 2 {8}{7,6}

-

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- Input: $\{8, 7, 6, 5, 4\}$
 - Iter 1: 8 assigned to set 1 $\{8\}\{\}$
 - Iter 2: 7 assigned to set 2 {8}{7}
 - Iter 3: 6 assigned to set 2 {8}{7,6}
 - Iter 4: 5 assigned to set 1 $\{8,5\}\{7,6\}$

Input: $\{8, 7, 6, 5, 4\}$

Iter 1: 8 assigned to set 1 $\{8\}\{\}$

- Iter 2: 7 assigned to set 2 {8}{7}
- Iter 3: 6 assigned to set 2 {8}{7,6}
- Iter 4: 5 assigned to set 1 $\{8,5\}\{7,6\}$
- Iter 5: 4 assigned to set 1 $\{8,5,4\}\{7,6\}$

Discrepancy: 4

The Differencing Algorithm by Karmarkar and Karp

Key idea: Reduce the length of the number list

- Replace two largest numbers a_i and a_j by $|a_i a_j|$
 - Commit to placing the two largest numbers in different sets
- Repeat until only one number left
- The remaining number = discrepancy
- Achieves better results than the greedy algorithm
 - Yields average discrepancies O(N^{-α log N}) with α = 0.72 (for real-valued NPP)
- Time complexity $O(N \log N)$ (sorting)

Input: $\{8, 7, 6, 5, 4\}$

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Input: $\{8, 7, 6, 5, 4\}$

Iter 1: Replace 8 and 7 by |8-7|=1 $\{6,5,4,1\}$

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Input: $\{8, 7, 6, 5, 4\}$

Iter 1: Replace 8 and 7 by |8 - 7| = 1{6,5,4,1}

Iter 2: Replace 6 and 5 by |6-5|=1 $\{4,1,1\}$

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Input: $\{8, 7, 6, 5, 4\}$

- Iter 1: Replace 8 and 7 by |8 7| = 1{6,5,4,1}
- Iter 2: Replace 6 and 5 by |6-5|=1 $\{4,1,1\}$
- Iter 3: Replace 4 and 1 by |4-1| = 3 $\{3,1\}$

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Input: $\{8, 7, 6, 5, 4\}$

- Iter 1: Replace 8 and 7 by |8 7| = 1{6, 5, 4, 1}
- Iter 2: Replace 6 and 5 by |6-5| = 1 $\{4,1,1\}$
- Iter 3: Replace 4 and 1 by |4-1| = 3{3,1}
- Iter 4: Replace 3 and 1 by |3 1| = 2{2} Discrepancy: 2

.....

Input: $\{8, 7, 6, 5, 4\}$

Iter 1: Replace 8 and 7 by |8-7|=1 $\{7, 5, 4\}\{8, 6\}$ $\{6, 5, 4, 1\}$ Iter 2: Replace 6 and 5 by |6 - 5| = 1 $\{5,4\}\{6,1\}$ $\{4, 1, 1\}$ Replace 4 and 1 by |4-1| = 3 $\{4\}\{1,1\}$ Iter 3: $\{3, 1\}$ Iter 4: Replace 3 and 1 by |3 - 1| = 2{3}{1} {2} {2}{} Discrepancy: 2

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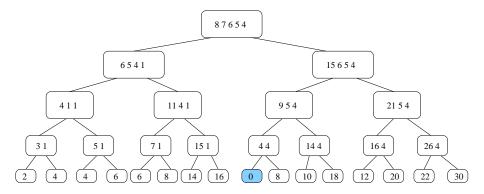
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Complete Algorithms

Complete greedy algorithm

- First try to put the largest number to the set with smaller sum.
- Then try to put it to the other set.
- ▶ I.e. search a tree of all 2^N possible partitions
- Complete differencing algorithm
 - ▶ First try to put the two largest numbers *a_i* and *a_i* to different sets
 - \implies Replace them by $|a_i a_j|$
 - Then try to put them into the same set
 - \implies Replace them by $a_i + a_j$

Complete Differencing Method: Example



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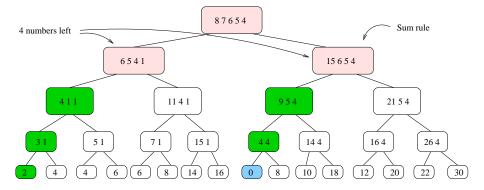
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Complete Differencing Method with Pruning

Pruning rules for the complete differencing method:

- ▶ If less than 5 numbers left, take the left branch
- ► If largest number ≥ sum of the rest of the numbers, place the largest number in one set and the others in the other set
- ▶ If a perfect partition has been found, stop.

Complete Differencing Method with Pruning: Example



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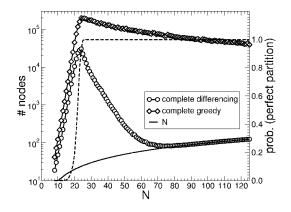
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Parameterization of NPP Instance Ensemble

- ▶ NPP instance: *N* random numbers *a_i*
- ▶ a_i < A
- ► $A = 2^{\kappa N} \implies$ worst case complexity of any (known) algorithm exponential in N for all $\kappa > 0$
- Typical complexity of NPP depends on κ

Phase Transition

- Instances: N random
 20-bit integers
- $\blacktriangleright A = 2^{20} \implies \kappa = 20/N$
- Phase transition at $\kappa_c \approx 20/24 \approx 0.83$



(From: S. Mertens: The Easiest Hard Problem: Number Partitioning, in: A.G. Percus, G. Istrate, C. Moore, eds., Computational Complexity and Statistical Physics, Oxford University Press (2006), p. 125-139)

Pseudo Polynomiality of NPP

▶ a_i < A

- Discrepancy has at most NA different values
- The search space can be explored in time $O(N^2A)$
- A polynomial algorithm?

Pseudo Polynomiality of NPP

▶ a_i < A

- Discrepancy has at most NA different values
- The search space can be explored in time $O(N^2A)$
- A polynomial algorithm?
 - Input size O(N log A)
 - \implies Running time is exponential in the size of the input!
- ▶ NP-hardness: input numbers allowed to be exponentially large in N
- If N is increased for constant A, NPP is eventually not NP-hard anymore

Analytical Results

(S. Mertens: Phase Transition in the Number Partition Problem, Phys. Rev. Lett. **81**, 4281 (1998))

- Analyze the average number of perfect partitions $\Omega(0)$
- It can be shown that

$$\log_2 \Omega(0) = N(\kappa_c - \kappa)$$

with

$$\kappa_c = 1 - rac{\log_2 N}{2N} - rac{1}{2N}\log_2\left(rac{\pi}{6}
ight)$$

▶ $\kappa < \kappa_c \implies$ Exponential number of perfect partitions \implies Easy phase

• $\kappa > \kappa_c \implies$ No perfect partitions \implies Hard phase

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Characteristics of the Easy Phase

- Exponential number of perfect partitions
- κ decreases \implies the number of perfect partitions increases
- \blacktriangleright For small κ perfect partitions found by heuristic algorithms

Characteristics of the Hard Phase

- Exponentially small probability of perfect partitions almost always unique
- Heuristic algorithms no better than blind search

Summary

- Number partitioning problem
- Two heuristic algorithms
 - Greedy
 - Differencing
- Phase transition in average complexity
 Phase transition in probability of perfect partitions
 - Easy phase where heuristic algorithms are effective
 - ► Hard phase where heuristic algorithms are no better than blind search

Analytical Results – Proof

(S. Mertens: The Easiest Hard Problem: Number Partitioning, in: A.G. Percus, G. Istrate, C. Moore, eds., Computational Complexity and Statistical Physics, Oxford University Press (2006), p. 125-139)

• Code a partition A with binary variables $s_i = \pm 1$:

 $\bullet \ s_i = +1 \implies i \in A \text{ and } s_i = -1 \implies i \notin A$

• The cost function: E = |D(s)| where

$$D(s) = \sum_{i=1}^{N} a_i s_i$$

- ▶ D can be interpreted as distance to the origin of a random walker in one dimension who takes steps to the right (s_i = +1) or left (s_i = −1) with random step sizes (a_i).
- Average number of walks ending at D:

$$\Omega(D) = \sum_{\{s_i\}} \left\langle \delta\left(D - \sum_{i=1}^{N} a_i s_i\right) \right\rangle$$

Analytical Results – Proof (continued)

▶ For a fixed walk {s_i} and large N the distance to the origin is Gaussian with mean

$$\langle D
angle = M \langle a
angle$$

and variance

$$\langle D^2 \rangle - \langle D \rangle^2 = M^2 (\langle a^2 \rangle - \langle a \rangle^2)$$

where $M = \sum_{j} s_{j}$.

Averaging over the random walk {s_i}:

$$\left[\langle D \rangle \right] = \left[M \right] \langle a \rangle = 0$$
$$\left[\langle D^2 \rangle \right] - \left[\langle D \rangle \right]^2 = \left[M^2 \right] \langle a^2 \rangle = N \langle a^2 \rangle$$

The probability of ending the walk at distance D

$$p(D) = \frac{1}{\sqrt{2\pi N \langle a^2 \rangle}} \exp\left(-\frac{D^2}{2N \langle a^2 \rangle}\right)$$

Analytical Results – Proof (continued)

- ▶ Note: The walk ends at even (odd) numbers for $\sum a_i$ even (odd)
- Average number of walks ending at D

$$\Omega(D) = 2^{N} 2p(D) = \frac{2^{N+1}}{\sqrt{2\pi N \langle a^2 \rangle}} \exp\left(-\frac{D^2}{2N \langle a^2 \rangle}\right)$$

Substituting

$$\langle a^2 \rangle = \frac{1}{3} 2^{2\kappa N} (1 - O(2^{-\kappa N}))$$

we get

$$\log_2 \Omega(0) = N(\kappa_c - \kappa)$$

with

$$\kappa_{c} = 1 - \frac{\log_2 N}{2N} - \frac{1}{2N}\log_2\left(\frac{\pi}{6}\right)$$