# T-79.232 Safety Critical Systems Case Study 4: B Method - Functions, Sequences and Nondeterminism

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### Functions in B - what kinds are there?

B provides a rich set of function types in its input language, and we'll describe each one in its turn. The complete list is:

- Partial functions
- Total functions
- Injective functions
- Surjective functions
- Bijective functions
- Lambda notation for functions

# T-79.5303: Case Study 4: B Method - Functions, Sequences and Nondeterminism 4-2 Partial functions

Basically, partial functions are relations, so they consist of pairs (s,t) where  $s \in S \land t \in T$ 

However, we have the additional requirement, that any member of S is mapped onto *at most* one element of T.

When we allow for some elements in set S not to be mapped onto an element of T we have partial functions. In math,

$$S \to T = \{ f \mid f \in S \leftrightarrow T \\ \land \forall s, t_1, t_2. \ (s \in S \land t_1 \in T \land t_2 \in T \Rightarrow \\ ((s \mapsto t_1 \in f \land s \mapsto t_2 \in f) \Rightarrow t_1 = t_2)) \}$$

For example, if we say  $favourite\_colour \in PERSON \rightarrow COLOUR$ , we are saying that people have one favourite colour or not at all.

### **Total Functions**

A *total function* is a partial function between sets S and T with the added requirement that every element of S must be mapped to exactly one element of T.

In mathematics,

$$S \to T = \{ f \mid f \in S \to T \land dom(f) = S \}$$

Now, if we declare that  $favourite\_colour \in PERSON \rightarrow COLOUR$ , we are stating that every person has exactly one favourite colour.

T-79.5303: Case Study 4: B Method - Functions, Sequences and Nondeterminism 4-4 Injective Functions

A function is injective between sets S and T, if it never maps two different members of S into the same element of T. Partial injections are defined as follows:

$$S \rightarrowtail T = \{ f \mid f \in S \leftrightarrow T \\ \land \forall s_1, s_2, t. \ (s_1 \in S \land s_2 \in S \land t \in T \Rightarrow \\ ((s_1 \mapsto t \in f \land s_2 \mapsto t \in f) \Rightarrow s_1 = s_2) \}$$

For total injections (injections that are also total functions), we have:

 $S \rightarrowtail T = \{ f \mid f \in S \rightarrowtail T \land f \in S \to T \}$ 

For example  $username \in PERSON \rightarrow ID$  associates a username to people in such a way that no two people get the same one. Also, there are some people who have no username at all.

# **Surjective Functions**

A function between sets S and T is *surjective* if every element of set T is reached from some element in set S.

For partial surjections we have:

$$S \twoheadrightarrow T = \{ f \mid f \in S \implies T \land ran(f) = T \}$$

For total surjections we have:

 $S \twoheadrightarrow T = \{ f \mid f \in S \twoheadrightarrow T \land f \in S \to T \}$ 

For example  $attends \in PERSON \implies SCHOOL$  says that every school is attended by some people, but there may be some people who do not attend any school.

### **Bijective Functions**

Bijective functions are functions which is total, injective and surjective.

In mathematical terms we write,

 $S \rightarrowtail T = \{ f \mid f \in S \rightarrowtail T \land f \in S \twoheadrightarrow T \}$ 

For example,  $married \in husbands \rightarrow wives$  says that there is exactly one wife for every husband, different husbands have different wives and every wife has a husband.

#### Lambda notation for functions

The lambda notation gets us closer to the 'implementation' language (= equations) of functions. It basically separates two entities - the variables in the function, and the operation that computes the function.

For example, we can define the squaring function of a natural number as follows:

square =  $\lambda x.(x \in \mathbb{N} \mid x^2)$ 

The nice thing about lambda notation is that you can add conditions on variables for the operation to occur. It also allows one to separate the domain of a function to disjoint parts.

For example, the following function divides the domain  $\mathbb{N}$  into two separate parts and performs a different operation on the input variable depending on whether is even or odd.

$$f = \lambda x. (x \in \mathbb{N} \land x \mod 2 = 1 \mid 3x+1\}$$
$$\cup \lambda x. (x \in \mathbb{N} \land x \mod 2 = 0 \mid x/2\}$$

#### B machine with Functions - 1

MACHINE ReadingSETS READER ; BOOK ; COPY ; RESPONSE = {yes, no}CONSTANTS copyofPROPERTIES copyof  $\in$  COPY  $\rightarrow$  BOOKVARIABLES hasread, readingINVARIANThasread  $\in$  READER  $\leftrightarrow$  BOOK $\land$  reading  $\in$  READER  $\rightarrowtail$  COPY

 $\land (reading; copyof) \cap hasread = \{\}$  **INITIALISATION** hasread :=  $\{\} \parallel reading := \{\}$ 

So, we have a machine where we have a number of COPIES of every BOOK, and every READER is reading a different COPY at any moment, as well as nobody is allowed to read a book a second time.

# B machine with Functions - 2

#### **OPERATIONS**

```
\begin{array}{l} \textbf{start}(\ rr, cc \ ) \ = \\ \textbf{PRE} \\ rr \in READER \ \land \ cc \in COPY \ \land \ copyof(cc) \not\in hasread[\ \{rr\} \ ] \\ \land \ rr \notin dom(\ reading \ ) \ \land \ cc \notin ran(\ reading \ ) \\ \textbf{THEN} \ reading \ := \ reading \ \cup \ \{\ rr \mapsto cc \ \} \\ \textbf{END} \ ; \end{array}
```

```
finished(rr, cc) =

PRE rr \in READER \land cc \in COPY \land cc = reading(rr)

THEN has read := has read \cup \{ rr \mapsto copyof(cc) \}

\parallel reading := \{ rr \} \blacktriangleleft reading

END;
```

### B machine with Functions - 3

```
resp \longleftarrow precurrentquery(rr) = PRE rr \in READER
THEN
IF rr \in dom(reading)
THEN resp := yes
ELSE resp := no
END
END;
```

```
bb \leftarrow currentquery(rr) =

PRE rr \in READER \land rr \in dom(reading)

THEN bb := copyof(reading(rr))

END;
```

#### B machine with Functions - 4

```
resp \leftarrow hasreadquery(rr, bb) =
```

**PRE**  $rr \in READER \land bb \in BOOK$ 

#### THEN

```
IF bb \in hasread[ \{ rr \} ]

THEN resp := yes

ELSE resp := no

END
```

END

END

#### Sequences - 1

Sequences are very useful in modelling some situations where we have a list with a definite order. B language provides a rich set of operations that are sequence specific, which will be given in the following:

Sequences may be formed by simply listing the elements as follows:

 $prime_1 := [Wilson, Heath, Wilson, Callaghan]$  $prime_2 := [Thatcher, Major]$ 

To concatenate two sequences we may use the  $\frown$  - operator:

 $prime_1 \frown prime_2 = [Wilson, Heath, Wilson, Callaghan, Thatcher, Major]$ 

#### Sequences - 2

Sequences may be reversed as well:

 $rev(prime_1) = [Callaghan, Wilson, Heath, Wilson]$ 

If we want to append an element to the front of the list, we use the  $\rightarrow$  operator:  $Callaghan \rightarrow prime_2 = [Callaghan, Thatcher, Major]$ 

Similarly we may ask the *first* element and *tail* of a sequence:

 $first(prime_1) = Wilson$  $tail(prime_1) = [Heath, Wilson, Callaghan]$ 

### Sequences - 3

We have a 'dual' operator pair for *first* and *tail* – namely *front* and *last*:  $front(prime_1) = [Wilson, Heath, Wilson]$  $last(prime_1) = Callaghan$ 

Appending to the back of the sequence is accomplished by  $\leftarrow$  operator:  $prime_2 \leftarrow Blair = [Thatcher, Major, Blair]$ 

To extract the first *n* elements of a sequence we use the  $\uparrow$  operator:  $prime_1 \uparrow 3 = [Wilson, Heath, Wilson]$ 

To extract all but the first *n* elements of a sequence we use the  $\downarrow$  operator:  $prime_1 \downarrow 3 = [Callaghan]$ 

#### Sequences - 4

The set of all possible sequences on a set *S* is defined as seq(S) (in other words, the infinite union of total functions from the set 1..*N* to the set *S*, where *N* grows without bounds):

 $seq(S) = \bigcup_{N=0}^{\infty} (1..N \to S)$ 

A more restrictive sequence is the injective sequence iseq(S). Here we are not allowed to repeat elements of *S* in the sequence, but we are not forced to include every element of *S* there:

 $iseq(S) = seq(S) \cap \mathbb{N} \rightarrowtail S$ 

Finally, a useful sequence is one where every element of set *S* appears exactly once perm(S). For this to make sense, *S* has to be finite:

 $perm(S) = 1..N \rightarrow S$ , where S is finite

B machine with Sequences - 1

MACHINE Results SETS RUNNER VARIABLES finish INVARIANT finish  $\in$  iseq(RUNNER) INITIALISATION finish := [] OPERATIONS finished(rr) = PRE  $rr \in RUNNER \land rr \notin ran(finish)$ THEN finish := finish  $\leftarrow rr$ END;

```
rr \leftarrow query(pp) =

PRE \ pp \in \mathbb{N}_1 \land pp \leq size(finish)

THEN \ rr := finish(pp)

END;
```

#### B machine with Sequences - 2

**disqualify**(pp) = **PRE**  $pp \in \mathbb{N}_1 \land pp \leq size(finish)$  **THEN**  $finish := finish \uparrow (pp-1) \frown (finish \downarrow pp)$ **END**;

 $ss \longleftarrow \mathbf{medals} =$  $ss := finish \uparrow 3$ 

END

# Nondeterminism in B machines

Nondeterminism is very important concept when modelling and verification is considered. A system has to work correctly on any input, and no matter what the sequence of correct and incorrect signals between communicating entities, a protocol must not deadlock.

B introduces ANY, CHOICE and SELECT statements to help in specifying non-determinism.

*ANY* has the least restrictions on non-determinism, *CHOICE* narrows down a potentially huge amount of alternatives by introducing many branches of alternatives, and *SELECT* allows one to control when particular 'branches' of alternatives are active.

# ANY x WHERE Q THEN T END

*x* is a new variable disjoint from any other variables defined in the system. Q is a predicate which must contain the type of *x* and how it may/may not relate to other variables in the system. *T* is a B statement that can use the value of *x* and other variables inside the machine. Notice that the value of *x* that is used in *T* is nondeterministically picked, but the choice must respect the predicate Q.

For example,

#### **ANY** *n* **WHERE** $n \in \mathbb{N}_1$ **THEN** *total* := *total* × *n* **END**

This statement multiplies the machine variable *total* by some nondeterministically picked natural number.

### Weakest Precondition for ANY

The proof obligation for the ANY statement will involve universal quantification, so that we prove that the invariant will be preserved no matter what value for x is chosen out of the possible ones:

#### $[ANY x WHERE Q THEN T END]P = \forall x. (Q \Rightarrow [T]P)$

For example, we see that the following precondition is identically true:

 $\begin{bmatrix} ANY \ n \ WHERE \ n \in \mathbb{N} \land n < 50 \ THEN \ total \ := \ n \times 2 \end{bmatrix} (total < 100) \\ \forall \ n \ .((n \in \mathbb{N} \land n < 50) \Rightarrow [total \ := \ n \times 2] (total < 100)) \\ \forall \ n \ .((n \in \mathbb{N} \land n < 50) \Rightarrow (n \times 2 < 100)) \\ \forall \ n \ .((n \in \mathbb{N} \land n < 50) \Rightarrow (n < 50)) \end{bmatrix}$ 

# **ANY** e **WHERE** $e \in S$ **THEN** x := e **END**

This construct is very heavily used in B, and sometimes it is called *nondeterministic assignment*.

It has a special symbol in B, written as follows:  $x :\in S$ 

The proof obligation for this is derived from the general ANY clause and it's the following:

 $[x :\in S]P = \forall x . (x \in S \Rightarrow P) \quad x \text{ not free in } S$ 

For example:

$$[x \in S](x \neq 3) = \forall x. (x \in S \Rightarrow x \neq 3)$$
$$= 3 \notin S$$

# CHOICE S OR T OR $\dots$ OR U END

This allows us to make a non-deterministic choice of a statement to execute. Each S, T,... is a valid B statement, and we could use such a construct e.g. to send a correct message or an incorrect message in a protocol.

For the proof obligation we get: [ **CHOICE** *S* **OR** *T* **END** ] $P = [S]P \land [T]P$ 

For example, the following weakest precondition is identically false:

[**CHOICE** x := 3**OR** x := 5**END**](x = 4)

# **SELECT** statement

This statement allows us to control which 'branches' of the options are active at one time, rather than having all branches active as in the **CHOICE** statement. The optional **ELSE** clause will be executed if none of the conditionals  $Q_n$  are satisfied. The syntax is as follows:

```
SELECT Q_1 THEN T_1
WHEN Q_2 THEN T_2
WHEN ...
WHEN Q_n THEN T_n
ELSE V
END
```

#### Weakest Precondition for SELECT

$$\begin{bmatrix} \textbf{SELECT } Q_1 \textbf{ THEN } T_1 \\ \textbf{WHEN } Q_2 \textbf{ THEN } T_2 \\ \dots \\ \textbf{WHEN } Q_n \textbf{ THEN } T_n \\ \textbf{END} \end{bmatrix} P = \begin{pmatrix} Q_1 \Rightarrow [T_1]P \\ \land Q_2 \Rightarrow [T_2]P \\ \dots \\ \land Q_n \Rightarrow [T_n]P \end{pmatrix}$$

#### B machine with Nondeterminism - 1

MACHINE Jukebox SETS TRACK CONSTANTS limit PROPERTIES limit  $\in \mathbb{N}_1$ VARIABLES credit, playset INVARIANT credit  $\in \mathbb{N} \land credit \leq limit \land playset \subseteq TRACK$ INITIALISATION credit  $:= 0 \parallel playset := \{\}$ 

# B machine with Nondeterminism - 2

#### **OPERATIONS**

pay(cc) = $PRE cc \in \mathbb{N}_1$  $THEN credit := min( \{ credit + cc, limit \} )$ END;

select(tt) =

**PRE** *credit*  $> 0 \land tt \in TRACK$ 

THEN

```
CHOICE credit := credit -1 \parallel playset := playset \cup \{ tt \}

OR playset := playset \cup \{ tt \}

END

END;
```

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 $tt \longleftarrow play =$   $PRE \ playset \neq \{\}$  THEN  $ANY \ tr$   $WHERE \ tr \in playset$   $THEN \ tt \ := \ tr \parallel playset \ := \ playset - \{ \ tr \}$  END END;

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penalty =
 SELECT credit > 0 THEN credit := credit - 1
 WHEN playset  $\neq$  {} THEN
 ANY pp
 WHERE pp  $\in$  playset
 THEN playset := playset - { pp }
 END
 ELSE skip
 END

END

### References

The material in this presentation has been obtained from

1. the b-method - an introduction. Steve Schneider. Palgrave, 2001. (This book belongs to the *cornerstones of computing* series by the same publisher)