

## Lecture 2: Positive Programs

### Outline

1. Background for rules
2. Rules and programs
3. Minimal models
4. Constructing the least model
5. Programs with variables
6. Expressive power

## Literals and Clauses

### Definitions.

1. A *literal* is either an atom  $a$  (a *positive literal*) or the negation of an atom  $\neg a$  (a *negative literal*).
2. A *clause* is a disjunction  $l_1 \vee \dots \vee l_n$  of literals  $l_1, \dots, l_n$ .
3. A *Horn clause* is a clause with at most one positive literal.
4. A *program clause*, or a *rule* for short, is a disjunction of literals  $a \vee \neg b_1 \vee \dots \vee \neg b_n$  with exactly *one* positive literal.

**Example.** The clauses  $\neg p \vee \neg q \vee \neg r$  and  $\neg p \vee q \vee \neg r$  are Horn clauses but  $p \vee \neg q \vee r$  is not. Only the second one is a program clause.

## 1. BACKGROUND FOR RULES

- Answer set programming adopts a rule-based syntax previously used in PROLOG, deductive databases, and expert systems.
- *Horn clauses* provide rule-based reasoning with a solid foundation:
  1. Rules can be interpreted as Horn clauses.
  2. Classical models determine the set of logical consequences  $C_n(\mathcal{R})$  associated with each set of rules  $\mathcal{R}$ .
- Horn clauses lend themselves for efficient implementation which makes them important from the computational point of view.
- Typically, applications require a more expressive language but for now we concentrate on rules corresponding to Horn clauses.

## 2. RULES AND PROGRAMS

Certain notational conventions are adopted for Horn clauses:

- A *rule*  $a \vee \neg b_1 \vee \dots \vee \neg b_n$  is written  $a \leftarrow b_1, \dots, b_n$  where  $a$  and  $b_1, \dots, b_n$  form the *head* and the *body* of the rule, respectively.
- A *constraint*  $\neg b_1 \vee \dots \vee \neg b_n$  is written  $\leftarrow b_1, \dots, b_n$  and it can be viewed as a rule with an empty head.
- A *fact*  $a$  ( $n = 0$ ) is a rule written without “ $\leftarrow$ ”.
- Full stops “.” are also used to separate rules in sets of rules.

**Definition.** A *positive program*  $P$  is a set of rules as defined above.

**Remark.** Here the word “positive” refers to the fact that rule bodies are negation-free. Forms of negation will be introduced later.

## Satisfaction and Entailment

**Definitions.** Assume rules and constraints based on a set of atoms  $\mathcal{P}$ .

1. A rule  $a \leftarrow b_1, \dots, b_n$  is *satisfied* in an interpretation  $I \subseteq \mathcal{P}$ , denoted  $I \models a \leftarrow b_1, \dots, b_n$ , iff  $\{b_1, \dots, b_n\} \subseteq I$  implies  $a \in I$ .
2. A constraint  $\leftarrow b_1, \dots, b_n$  is *satisfied* in an interpretation  $I \subseteq \mathcal{P}$ , denoted  $I \models \leftarrow b_1, \dots, b_n$ , iff  $\{b_1, \dots, b_n\} \not\subseteq I$ .
3. An interpretation  $I \subseteq \mathcal{P}$  is a *model* of a set of rules and constraints  $PUC$ , denoted  $M \models PUC$ , iff  $M \models r$  for each  $r \in PUC$ .
4. An atom  $a$  is a *logical consequence* of  $PUC$  iff  $a \in M$  for every interpretation  $M \subseteq \mathcal{P}$  such that  $M \models PUC$ .

**Proposition.** Every positive program  $P$  is *satisfiable* (has a model).

**Proof.** The interpretation  $M = \text{Hb}(P)$  is trivially a model of  $P$ .  $\square$

## 3. MINIMAL MODELS

**Definition.**

1. An interpretation  $M \subseteq \mathcal{P}$ , represented as the set of atoms true in  $M$ , is smaller than another interpretation  $N \subseteq \mathcal{P}$  iff  $M \subset N$ .
2. An interpretation  $M \subseteq \text{Hb}(P)$  is a *minimal model* of a (positive) program  $P$  iff  $M \models P$  and there is no smaller model  $N \models P$ .

**Example.** Consider the following positive program:

$$P = \{q \leftarrow r. \quad r \leftarrow p, q. \}$$

- The interpretation  $M = \{q, r\}$  is a model of  $P$ .
- However,  $M$  is not minimal because  $N = \emptyset$  is also a model of  $P$ .
- But, in contrast,  $N$  is a minimal model of  $P$ .

## Translating Constraints into Rules

- Any set Horn clauses  $S$ , effectively a union  $PUC$  of a positive program  $P$  and a set of constraints  $C$ , is not satisfiable in general.
- E.g.,  $\{p, \neg p\}$  corresponding to  $\{p\} \cup \{\leftarrow p\}$  has no models.
- Any set of constraints  $C$  can be translated into a positive program

$$\text{Tr}_{\text{RULE}}(C) = \{\perp \leftarrow b_1, \dots, b_n \mid \leftarrow b_1, \dots, b_n \in C\}$$

where  $\perp$  is a new atom not appearing in  $\text{Hb}(P)$  nor  $\text{Hb}(C)$ .

**Proposition.** A set of Horn clauses  $S$ , viewed as a union  $PUC$  in the way explained above, is satisfiable  $\iff P \cup \text{Tr}_{\text{RULE}}(C) \not\models \perp$ .

**Example.** The *unsatisfiability* of  $\{p, \neg p\}$  can be determined using the translation given above:  $\{p\} \cup \text{Tr}_{\text{RULE}}(\{\leftarrow p\}) = \{p. \quad \perp \leftarrow p. \} \models \perp$ .

## Properties of Minimal Models (I)

**Theorem.** If  $M_i \subseteq \text{Hb}(P)$  (where  $i \in I$ ) is a collection of models for a positive program  $P$ , then  $M = \bigcap \{M_i \mid i \in I\}$  is also a model of  $P$ .

**Proof.** Suppose that  $M \not\models P$ .

- $\implies \exists a \leftarrow b_1, \dots, b_n \in P$  such that  $\{b_1, \dots, b_n\} \subseteq M$  but  $a \notin M$
- $\implies \{b_1, \dots, b_n\} \subseteq M_i$  for all  $i \in I$
- $\implies a \in M_i$  for all  $i \in I$  because  $M_i \models P$ ,
- $a \leftarrow b_1, \dots, b_n \in P$  and  $M_i \models a \leftarrow b_1, \dots, b_n$
- $\implies a \in M = \bigcap \{M_i \mid i \in I\}$ , a contradiction.

Thus  $M \models P$  is necessarily the case.  $\square$

## Properties of Minimal Models (II)

**Theorem.** A positive program  $P$  has at least one minimal model.

**Proof.** We will cover the case when  $|\text{Hb}(P)| = n$  is finite (a generalization for the infinite case requires *transfinite induction*).

Since  $P$  is a positive program, we know that  $M_0 = \text{Hb}(P) \models P$ . Then define a decreasing sequence  $M_0 \supseteq \dots \supseteq M_i \supseteq \dots$  of models for  $P$ :

- If  $M_i$  is a minimal model of  $P$ , let  $M_{i+1} = M_i$ .
- If  $M_i$  is not a minimal model of  $P$ , it has a model  $N \subset M_i$ .  
Let  $M_{i+1} = N$ .

Assuming that  $M_i \models P$  is never minimal implies that the sequence is properly decreasing for all  $i \geq 0$ . A contradiction when  $i > n$ .  $\square$

## Properties of Minimal Models (III)

**Theorem.** Every positive program  $P$  has a unique minimal model, the *least model*  $\text{LM}(P)$  of  $P$ , which is the intersection of its all models.

**Proof.** Since  $P$  has at least one minimal model (shown above), let us assume that  $P$  had two minimal models, say  $M_1$  and  $M_2$ .

- $\Rightarrow M_1 \cap M_2 \models P$
- $\Rightarrow M_1 \cap M_2 = M_1$  and  $M_1 \cap M_2 = M_2$  ( $M_1$  and  $M_2$  are minimal)
- $\Rightarrow M_1 = M_2$ .

Thus  $\text{LM}(P) \subseteq M$  holds for every  $M \models P$  because  $\text{LM}(P)$  is unique.

Since  $\text{LM}(P) \models P$ , we obtain  $\bigcap \{M \subseteq \text{Hb}(P) \mid M \models P\} = \text{LM}(P)$ .  $\square$

## Example

The idea of the preceding proof can be demonstrated using

$$P_n = \{p_0 \leftarrow p_0. \ p_1 \leftarrow p_1. \ p_2 \leftarrow p_2. \ \dots \ p_n \leftarrow p_n. \}$$

which is a positive program with a finite number, i.e.,  $n + 1$ , of rules.

- The interpretation  $M_0 = \text{Hb}(P_n) = \{p_0, \dots, p_n\}$  is a model of  $P$  but not minimal because  $M_1 = \{p_1, \dots, p_n\} \models P$ .
- A generalization for  $i > 0$ : the interpretation  $M_i = \{p_i, \dots, p_n\}$  is a model of  $P_n$  but not minimal because  $M_{i+1} = \{p_{i+1}, \dots, p_n\} \models P_n$ .
- When  $i$  equals to  $|\text{Hb}(P_n)| = n + 1$ , we have a minimal model

$$M = \bigcap_{i=0}^{n+1} M_i = \emptyset.$$

## Answer Sets

**Corollary.** For any positive program  $P$ ,

$$\text{LM}(P) = \{a \in \text{Hb}(P) \mid P \models a\}.$$

- By this corollary, the least model of a positive program  $P$  provides means to answer queries about atoms in  $\text{Hb}(P)$ .
- Thus  $\text{LM}(P)$  is the unique *answer set* associated with  $P$ .

**Example.** For  $P = \{a \leftarrow b, c. \ b \leftarrow a, c. \ c \leftarrow a, b. \}$ ,

1.  $\text{LM}(P \cup \{a. \}) = \{a\}$  and
2.  $\text{LM}(P \cup \{a. \ b. \}) = \{a, b, c\}$ .

Thus  $P \cup \{a. \} \not\models c$  but  $P \cup \{a. \ b. \} \models c$ .

## 4. CONSTRUCTING THE LEAST MODEL

**Definition.** Let  $P$  be a positive logic program. Then define an *operator*  $T_P : \mathbf{2}^{\text{Hb}(P)} \rightarrow \mathbf{2}^{\text{Hb}(P)}$  on interpretations  $I \subseteq \text{Hb}(P)$  as follows:

$$T_P(I) = \{a \in \text{Hb}(P) \mid a \leftarrow b_1, \dots, b_n \in P \text{ and } \{b_1, \dots, b_n\} \subseteq I\}.$$

An interpretation  $I$  is a *fixpoint* of the operator  $T_P$  iff  $T_P(I) = I$ .

A fixpoint  $I$  is the *least fixpoint* of  $T_P$  iff  $I \subseteq I'$  for every  $I' = T_P(I')$ .

**Example.** Let us analyze  $P = \{a \leftarrow a. \ b. \ c \leftarrow b. \ d \leftarrow a, b. \}$ .

1. Now  $T_P(\{a\}) = \{a, b\}$  and  $T_P(\{a, b\}) = \{a, b, c, d\}$ ,
2. the interpretation  $M_1 = \{a, b, c, d\}$  is a fixpoint of  $T_P$  since  $T_P(M_1) = \{a, b, c, d\} = M_1$ , and
3. the interpretation  $M_2 = \{b, c\}$  is the least fixpoint of  $T_P$ .

## Properties of the Least Fixpoint (I)

**Proposition.** For a positive program  $P$ , the operator  $T_P$  has the least fixpoint  $\text{lfp}(T_P) = \bigcap \{M \subseteq \text{Hb}(P) \mid M = T_P(M)\}$ .

**Proof.** Every monotonic operator has a least fixpoint (Knaster-Tarski) which is unique. For  $T_P$ , we denote this fixpoint by  $\text{lfp}(T_P)$ .

For the intersection property, it is sufficient to note that by definition  $\text{lfp}(T_P) \subseteq M$  for any  $M = T_P(M)$ , and  $M = \text{lfp}(T_P)$  in particular.  $\square$

The unique fixpoint  $\text{lfp}(T_P)$  can be constructed iteratively:

**Definition.** For a positive program  $P$ , define a sequence of interpretations by setting  $T_P \uparrow 0 = \emptyset$ ,  $T_P \uparrow i + 1 = T_P(T_P \uparrow i)$  for  $i > 0$ , and the *limit*  $T_P \uparrow \infty = \bigcup_{i=0}^{\infty} T_P \uparrow i$  of the sequence.

## Properties of $T_P$

**Proposition.** An interpretation  $M \subseteq \text{Hb}(P)$  is a model of a positive program  $P$  iff  $T_P(M) \subseteq M$ .

**Proof.** For any interpretation  $M \subseteq \text{Hb}(P)$ ,  $M \models P$

$$\iff \exists a \leftarrow b_1, \dots, b_n \in P \text{ such that } \{b_1, \dots, b_n\} \subseteq M \text{ but } a \notin M$$

$$\iff \exists a \in T_P(M) \text{ such that } a \notin M \iff T_P(M) \not\subseteq M. \quad \square$$

**Proposition.** (Monotonicity) For a positive program  $P$ ,

$$M \subseteq N \subseteq \text{Hb}(P) \text{ implies } T_P(M) \subseteq T_P(N).$$

**Proof.** For any atom  $a \in \text{Hb}(P)$ , we have that  $a \in T_P(M)$

$$\implies \exists a \leftarrow b_1, \dots, b_n \in P \text{ such that } \{b_1, \dots, b_n\} \subseteq M$$

$$\implies \exists a \leftarrow b_1, \dots, b_n \in P \text{ such that } \{b_1, \dots, b_n\} \subseteq N \text{ (} M \subseteq N \text{)}$$

$$\implies a \in T_P(N). \quad \square$$

## Properties of the Least Fixpoint (II)

**Theorem.** For a positive program  $P$ ,  $\text{lfp}(T_P) = T_P \uparrow \infty = \text{LM}(P)$ .

**Proof.** We will prove the claim  $\text{lfp}(T_P) = T_P \uparrow \infty$  when  $P$  is *finite*; the infinite case uses *transfinite induction* and the *compactness* of  $T_P$ .

( $\subseteq$ ) The monotonicity of  $T_P$  guarantees that the sequence of interpretations  $T_P \uparrow i$  is increasing. Hence  $T_P(T_P \uparrow i) = T_P \uparrow i$  for some  $i \geq 0$ . Thus  $\text{lfp}(T_P) \subseteq T_P \uparrow i \subseteq T_P \uparrow \infty$ .

( $\supseteq$ ) It follows by induction on  $i$  that  $T_P \uparrow i \subseteq \text{lfp}(T_P)$  for every  $i \geq 0$ .

For  $\text{lfp}(T_P) = \text{LM}(P)$ , we note the following:

( $\subseteq$ ) It follows by induction that  $T_P \uparrow i \subseteq \text{LM}(P)$  for every  $i \geq 0$ .

( $\supseteq$ ) Any fixpoint  $M = T_P(M)$  is also a model of  $P$ . Thus the intersection of models, i.e.  $\text{LM}(P)$ , is contained in  $M$ .  $\square$

### Example

Reconsider the program  $P = \{a \leftarrow a. \ b. \ c \leftarrow b. \ d \leftarrow a, b. \}$ :

$$T_P \uparrow 0 = \emptyset,$$

$$T_P \uparrow 1 = T_P(T_P \uparrow 0) = T_P(\emptyset) = \{b\},$$

$$T_P \uparrow 2 = T_P(T_P \uparrow 1) = T_P(\{b\}) = \{b, c\},$$

$$T_P \uparrow 3 = T_P(T_P \uparrow 2) = T_P(\{b, c\}) = \{b, c\}, \dots$$

$$T_P \uparrow i + 1 = T_P(T_P \uparrow i) = T_P(\{b, c\}) = \{b, c\}, \dots$$

$$\implies T_P \uparrow \infty = \bigcup_{i=0}^{\infty} T_P \uparrow i = \{b, c\} = \text{Ifp}(T_P) = \text{LM}(P).$$

**Remarks.** If  $P$  is a *finite* positive program (as above), then  $\text{Ifp}(T_P)$  is always reached with a finite number of steps. For each  $a \in \text{Ifp}(P)$ , there is a finite  $i \geq 0$  such that  $a \in T_P \uparrow i$ , even if  $P$  is *infinite*!

### Answer Sets

- The semantics of a positive program  $P$  involving variables is determined by the respective *ground program*  $\text{Gnd}(P)$ .
- It is possible to view  $\text{Gnd}(P)$  as a propositional program and it becomes infinite if  $P$  has function symbols and variables.

**Definition.** Let  $P$  be a positive program—potentially involving variables. The unique *answer set* of  $P$  is  $\text{LM}(\text{Gnd}(P))$ .

This set gives also the correctness criterion for *query evaluation*:

**Proposition.** Suppose that  $Q(\vec{t})$  is a query involving variables  $x_1, \dots, x_n$  for a positive program  $P$ . Then  $P \models \exists x_1 \dots \exists x_n Q(\vec{t}) \iff$  there is a ground substitution  $\theta$ , which replaces each variable  $x_i$  with a ground term  $t_i \in \text{Hu}(P)$ , such that  $Q(\vec{t})\theta \in \text{LM}(\text{Gnd}(P))$ .

## 5. PROGRAMS WITH VARIABLES

- Disregarding any non-logical features, logic programs and deductive databases can be viewed as sets of *rules* of the form

$$P(\vec{t}) \leftarrow P_1(\vec{t}_1), \dots, P_n(\vec{t}_n)$$

where  $P(\vec{t})$  and  $P_i(\vec{t}_i)$ 's are *atomic formulas* involving lists of terms  $\vec{t}, \vec{t}_1, \dots, \vec{t}_n$  as their arguments.

- Variables appearing in rules are universally quantified.
- Each set of rules  $P$ , also called a *positive program* in the sequel, has a Herbrand base  $\text{Hb}(P)$  associated with it.
- A rule  $P(\vec{t}) \leftarrow P_1(\vec{t}_1), \dots, P_n(\vec{t}_n)$  with variables  $x_1, \dots, x_m$  stands for its all *ground instances*, each of which is obtained by substituting the variables  $x_1, \dots, x_m$  by some ground terms  $s_1, \dots, s_m$ .

### Example

Consider a positive program  $P$  with the following rules

$$R(a, c). \quad R(b, c). \quad Q(x) \leftarrow R(x, y).$$

1. The ground program over  $\text{Hu}(P) = \{a, b, c\}$  contains the rules

$$R(a, c). \quad Q(a) \leftarrow R(a, a). \quad Q(a) \leftarrow R(a, b). \quad Q(a) \leftarrow R(a, c).$$

$$R(b, c). \quad Q(b) \leftarrow R(b, a). \quad Q(b) \leftarrow R(b, b). \quad Q(b) \leftarrow R(b, c).$$

$$Q(c) \leftarrow R(c, a). \quad Q(c) \leftarrow R(c, b). \quad Q(c) \leftarrow R(c, c).$$

2. The answer set is  $\text{LM}(\text{Gnd}(P)) = \{R(a, c), R(b, c), Q(a), Q(b)\}$ .
3. As earlier, this interpretation captures intended answers to queries:

$$P \models R(a, c) ? \quad \text{yes} \qquad P \models R(a, d) ? \quad \text{no}$$

$$P \models Q(a) ? \quad \text{yes} \qquad P \models Q(c) ? \quad \text{no}$$

## 6. EXPRESSIVE POWER

Rules are expressive enough to cover basic operations on relations as present in *relational algebra* (SQL):

1. Union:  $\text{EUNational}(x) \leftarrow \text{Finn}(x).$   
 $\text{EUNational}(x) \leftarrow \text{Swede}(x).$
2. Intersection:  $\text{Father}(x) \leftarrow \text{Parent}(x), \text{Man}(x).$
3. Projection:  $\text{Parent}(x) \leftarrow \text{Parent}(x, y).$
4. Selection:  $\text{Millionaire}(x) \leftarrow \text{Assets}(x, y), \text{Greater}(y, 999999).$
5. Composition:  $\text{Result}(x, y) \leftarrow \text{Student}(x, i), \text{Grade}(i, y).$

## OBJECTIVES

- You are able to define minimal models and the least model for positive programs and to prove simple properties about them.
- You know the interconnection between the least model of a positive program and its logical consequences.
- You are able to construct the least model for the given positive program  $P$  by calculating the least fixpoint of  $T_P$ .
- You have some preliminary ideas how minimal models are exploited in knowledge representation.
- You are aware of the basic similarities and differences of relational algebra and rule-based languages.

## Contrast with Relational Algebra

Unlike SQL (stands for Structured Query Language), positive programs enable recursive definitions.

**Example.** E.g., the *transitive closure* of a relation is expressible:

$$\text{Connection}(x, y) \leftarrow \text{Flight}(x, y).$$

$$\text{Connection}(x, y) \leftarrow \text{Flight}(x, z), \text{Connection}(z, y).$$

On the other hand, the conditions used in the form of rules considered so far cannot refer to *complements* of relations as in SQL.

**Example.** However, it is not trivial to add negation ( $\sim$  below):

$$\text{Man}(a). \text{Man}(b). \text{Man}(c).$$

$$\text{Shaves}(c, x) \leftarrow \text{Man}(x), \sim \text{Shaves}(x, x). \text{Shaves}(a, a).$$

## TIME TO PONDER

Consider two positive programs  $P_1$  and  $P_2$  and their union  $P_1 \cup P_2$ .

Which of the following do hold in general?

1.  $\text{LM}(P_1 \cup P_2) \subseteq \text{LM}(P_1) \cup \text{LM}(P_2).$
2.  $\text{LM}(P_1) \cup \text{LM}(P_2) \subseteq \text{LM}(P_1 \cup P_2).$