Computations in trees (Sec. 2.6)

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Computation in Trees

 Restrictions R and knowledge that the network is a tree

- every node knows if whether it is a leaf

- T[x y] = sub tree from x with (x,y) removed
- d[x, y] = longest distance from x to nodes in T[y - x]

Full Saturation

- Works with any number of initiators
- 1. Activation, starting from initiators activate all nodes
- 2. Saturation, started by leaf nodes, an unique pair of neighbors is selected.
- 3. Resolution, started by the selected pair; unique to application
- A plug-in algorithm
- M[Full Saturation] = $2n + k_* 2$
- T[Full Saturation] = Max{Min{d(I, y)+t(y)}+d(I,y); y∈I, I∈L}

Minimum Finding

- During saturation include smallest known value in M
- Resolution is a notification to children started by the two saturated nodes
- M[MinF Tree] = 3n k_∗ 4
- T [MinF Tree] = T[Full Saturation] + Max{d(s, x) : s∈Sat, x∈V}

Distributed Function Evaluation

- Semigroup Operations
 - f is associative and commutative over all subsets of input values
 - e.g. min, max, sum, product
- Cardinal Statistics
 - also solvable by Full Saturation
 - e.g. average, standard deviation

Finding Eccentricities

- The eccentricity of a node is the largest distance from a node to any other node.
- Trivial for a single node using broadcast and convergecast

-M=2(n-1)

• Slow to do to all the nodes in a tree

Finding Eccentricities cont.

- Using Full Saturation
- During resolution:
 - Send child y (of parent x) the only piece of missing information:
 - The maximum distance of nodes in T[x-y]
- M[Eccentricities] = $3n + k_* 4$
- T[Eccentricities] = T[MinF Tree]

Center Finding

- Can be done with Eccentricities and an additional saturation and resolution
- Theories:
 - In a tree there is on or two centers (who are neighbors)
 - In a tree all centers lie on all diametrical paths
 - node x is a center only if $d_1(x)-d_2(x) \le 1$; if strict inequality, then x is the only center

Center Finding cont.

- An entity x only needs to know d[x, y] for each of it neighbors y
- The Eccentricities provides this information
- Same costs
- For a plug-in: only move toward the center

Other computations

- Finding a median
- A median has the smallest average distance to all other nodes
 - In a tree there is an unique median or a neighboring pair
 - Entity x is a median iff $G[x,y] \ge 0$ for all neighbors y
 - If x is not the median, there exists a unique neighbor y such that G[y,x]<0; such a neighbor lies on the path to the median
- G[x, y] = n + 2 2 * | T[y x] |

Other computations cont.

- Finding diametral paths
 A node x is on a diametral path iff
 - $d_1(x)+d_2(x)=d$

Rooted Trees

- a root is a strong assumption
 unsolvable under R
- convergecast: simplified saturation
- can be totally ordered by a protocol
 choosing a random entity possible