Introduction to Theoretical Computer Science (T)
Session 9
Answers to demonstration exercises
4. Problem: Show that pushdown automata with two stacks (rather than just one as permitted by the standard definition) would be capable of recognizing exactly the same languages as Turing machines.
Solution: We first show that a two-stack pushdown automaton can simulate a Turing machine. The only difficulty is to find a way to simulate the Turing machine tape using two stacks. This can be done using a construction that is similar to the one presented in the first problem: the first stack holds the part of tape that is left to the read/write head (in reversed order), and the second stack holds the symbols that are right to the head.


The computation of the automaton can be divided into two parts:
(a) Initialization, when the automaton copies the input to stack $S_{1}$ one symbol at a time, and then moves it, again one-by-one, to stack $S_{2}$. (With the exception of the first symbol).
(b) Simulation, where the automaton decides its next transition by examining the top symbol of $S_{1}$. If the machine moves its head to left, the top element of $S_{1}$ is moved into $S_{2}$. If it moves to the other direction, the top element of $S_{2}$ is moved to $S_{1}$.

A two-stack pushdown automaton that is formed using these principles simulates a given Turing machine. The formal details are presented in an appendix.
Next we show that we can simulate a two-stack pushdown automaton using a Turing machine. This can be done trivially using a two tape nondeterministic Turing machine where both stacks are stored on their own tapes.
5. Problem: Extend the notion of a Turing machine by providing the possibility of a twoway infinite tape. Show that nevertheless such machines recognize exactly the same languages as the standard machines whose tape is only one-way infinite.
Solution: A Turing machine with a two-way infinite tape works otherwise in a same way than a standard machine except that the position of the tape start symbol ( $>$ ) is not fixed and it can move in a same way than the end symbol $(<)$. The tape positions are indexed by the set $\mathbb{Z}$ of integers where 0 denotes the initial position of $>$.
We can simulate such a Turing machine by a two-track one-way Turing machine. Conceptually, we divide the tape into two parts: upper and lower. The upper part holds the two-way tape cells $i \geq 0$ and the lower part cells $i<0$. For example, a two-way tape:

is expressed as a one-way tape:


In practice the construction of two tracks is done by replacing the alphabet $\Sigma$ by a new alphabet $\Sigma^{\prime}=\left(\Sigma \cup\left\{<^{\prime},>^{\prime}\right\}\right) \times\left(\Sigma \cup\left\{<^{\prime},>^{\prime}\right\}\right)$. Each symbol of $\Sigma^{\prime}$ thus denotes two symbols of $\Sigma$. The symbols $\left.\left\{<^{\prime},\right\rangle^{\prime}\right\}$ are new symbols that denote the start and end symbols of the original tape. So, the above example is expressed as:


We still need a way to decide which tape-half is used. The easiest way to do this is to define a mirror image state $q^{\prime}$ for each state $q$. When the machine is in state $q$, it examines only the upper track when it decides what move to take next (tape head is on right side of the tape). Similarily, in state $q^{\prime}$ it examines only the lower symbol (tape head is on the left side). Since the lower tape is in a reversed order, all tape head moving instructions have to be also reversed.
The formal definition of this construction is presented in an appendix.
6. Problem: Show that Turing machines whose tape alphabet contains at most two symbols in addition to the input symbols are capable of recognising exactly the same languages as the standard machines.

## Solution:

Let $M=\left(Q, \Sigma, \Gamma, \delta, q_{0}, q_{\mathrm{acc}}, q_{\mathrm{rej}}\right)$ be a Turing machine such that $|\Gamma-\Sigma|>2$. We want to construct a machine $M^{\prime}$ such that $\Gamma^{\prime}=\{0,1\}$. Let $\Gamma=\left\{a_{1}, \ldots, a_{n}\right\}$. The basic idea of the construction is to identify the elements of $\Gamma$ with the integers $\{1, \ldots, n\}$ and represent them as $k$-bit integers, where $k=\left\lceil\log _{2}(|\Gamma|)\right.$. In other words, each element of $M$ 's tape alphabet is replaced with $k$ bits. For example, suppose that $N=3$ and the tape has the input $a_{1} a_{2} a_{3}$. In this case the encoding is:

$$
\begin{array}{|l|l|l|l|l|}
\hline> & \underline{a_{1}} & a_{2} & a_{3} & <
\end{array} \begin{array}{|l|l|l|l|l|l|l|l|}
\hline> & \underline{0} & 1 & 1 & 0 & 1 & 1 & < \\
\hline
\end{array}
$$

The transition function of $M^{\prime}$ is defined so that for each step of $M, M^{\prime}$ does first $k$ steps where it first decides what symbol of $\Gamma$ is encoded in the tape cells to the right of the read/write head. This can be done using a Turing machine that reads $k$ symbols from the tape while moving its head to right at each step and that remembers the input in its states. For example, if $k=3$, then the following Turing machine may be used:


If the machine ends in the state 011 , then the input symbol is $a_{3}$ since $011_{2}=3_{10}$. The symbol that is written to the tape is similarily done using $k$ different transitions. Finally, the tape head is moved $k$ steps to the correct direction.

## Appendix: the formalisation of solution 5

Let $M=\left(Q, \Sigma, \Gamma, \delta, q_{0}, q_{\text {acc }}, q_{\mathrm{rej}}\right)$ be a two-way tape Turing machine. Define a standard Turing machine $M^{\prime}$ as follows:

$$
\begin{aligned}
M^{\prime} & =\left(Q^{\prime}, \Sigma^{\prime}, \Gamma^{\prime}, \delta^{\prime}, q_{0}, q_{\mathrm{acc}}, q_{\mathrm{rej}}\right) \\
Q^{\prime} & =Q \cup\left\{q^{\prime} \mid q \in Q\right\} \\
\Sigma^{\prime} & =\left(\Sigma \cup\left\{<^{\prime},>^{\prime}\right\}\right) \times\left(\Sigma \cup\left\{<^{\prime},>^{\prime}\right\}\right) \\
\Gamma^{\prime} & =\left(\Gamma \cup\left\{<^{\prime},>^{\prime}\right\}\right) \times\left(\Gamma \cup\left\{<^{\prime},>^{\prime}\right\}\right)
\end{aligned}
$$

The transition function $\delta^{\prime}$ is defined as follows:

$$
\begin{aligned}
\delta^{\prime}= & \left\{\left(q_{1},\langle a, \gamma\rangle, q_{2},\langle b, \gamma\rangle, \Delta\right) \mid\left(q_{1}, a, q_{2}, b, \Delta\right) \in \delta, \gamma \in \Gamma^{\prime}\right\} \\
& \left.\cup\left\{\left(q_{1},\left\langle\sigma^{\prime}, \gamma\right\rangle, q_{2},\langle b, \gamma\rangle, \Delta\right) \mid\left(q_{1}, \sigma, q_{2}, b, \Delta\right) \in \delta, \gamma \in \Gamma^{\prime}, \sigma \in\{<,\rangle\right\}\right\} \\
& \cup\left\{\left(q_{1}^{\prime},\langle\gamma, a\rangle, q_{2}^{\prime},\langle\gamma, b\rangle, \bar{\Delta}\right) \mid\left(q_{1}, a, q_{2}, b, \Delta\right) \in \delta, \gamma \in \Gamma^{\prime}\right\} \\
& \cup\left\{\left(q^{\prime},\langle\gamma, a\rangle, q_{\mathrm{end}},\langle\gamma, b\rangle, \bar{\Delta}\right) \mid\left(q, a, q_{\mathrm{end}}, b, \Delta\right) \in \delta, q_{\mathrm{end}} \in\left\{q_{\mathrm{acc}}, q_{\mathrm{rej}}\right\}, \gamma \in \Gamma^{\prime}\right\} \\
& \left.\cup\left\{\left(q_{1}^{\prime},\left\langle\gamma, \bar{\sigma}^{\prime}\right\rangle, q_{2}^{\prime},\langle\gamma, b\rangle, \bar{\Delta}\right) \mid\left(q_{1}, \sigma, q_{2}, b, \Delta\right) \in \delta, \gamma \in \Gamma^{\prime}, \sigma \in\{<,\rangle\right\}\right\} \\
& \left.\left.\cup\left\{\left(q,>, q^{\prime},\right\rangle, R\right),\left(q^{\prime},\right\rangle, q,>, R\right) \mid q \in Q\right\},
\end{aligned}
$$

where $\bar{L}=R, \bar{R}=L, \overline{<}=>$ and $\overline{>}=<$.

