## Solutions

1. (a) We start by abstracting temperatures so that there are only two possible values high and normal (i.e., not high). These values are captured by the Boolean variable $T$ below: if $T=$ true, then the temperature is too high, and if $T=$ false, the temperature is normal. We use the following nodes (random variables) in the network:

- $F_{A}$ - The alarm is faulty.
- $T$ - The temperature of the core is too high.
- $F_{G}$ - The gauge is faulty.
- $G$ - The gauge shows a high temperature.
- $A$ - The alarm goes off.

Each variable is a Boolean one, i.e., takes T or F as its value. The dependencies described in the exercise text lead us to construct the following Bayesian network as a model of the domain:

(b) The network is not a polytree, since there are two different paths from variable $T$ to variable $G$.
(c) See (a) for the abstraction of temperatures, i.e., the values of variable $T$. The CPT associated with $G$ is the following:

| $T$ | $F_{G}$ | $P(G)$ | $P(\neg G)$ |
| :---: | :---: | :---: | :---: |
| T | T | $y$ | $1-y$ |
| T | F | $x$ | $1-x$ |
| F | T | $1-y$ | $y$ |
| F | F | $1-x$ | $x$ |

(d) The CPT associated with $A$ is given below:

| $G$ | $F_{A}$ | $P(A)$ | $P(\neg A)$ |
| :---: | :---: | :---: | :---: |
| T | T | 0 | 1 |
| T | F | 1 | 0 |
| F | T | 0 | 1 |
| F | F | 0 | 1 |

Thus we may conclude that there is a logical relationship among the three variables involved: $A \leftrightarrow G \wedge \neg F_{A}$.
(e) The distribution $\mathbf{P}\left(T \mid \neg f_{A}, \neg f_{G}, a\right)$ can be determined for instance as follows:

$$
\begin{aligned}
& \mathbf{P}\left(T \mid a, \neg f_{A}, \neg f_{G}\right) & & \\
= & \mathbf{P}\left(T \mid a, \neg f_{A}, g, \neg f_{G}\right) & & \left\{a \leftrightarrow g \wedge \neg f_{A}, \neg f_{A}, a\right\} \models g \\
= & \mathbf{P}\left(T \mid g, \neg f_{G}\right) & & \text { Cond. Ind. mb }(T)=\left\{F_{G}, G\right\} \\
= & \alpha \mathbf{P}\left(g, \neg f_{G} \mid T\right) \mathbf{P}(T) & & \text { Bayes \& Normalization } \\
= & \alpha \mathbf{P}\left(g, \neg f_{G}, T\right) & & \text { Cond. prob. } \\
= & \alpha \mathbf{P}\left(g \mid \neg f_{G}, T\right) \mathbf{P}\left(\neg f_{G} \mid T\right) \mathbf{P}(T) . & & \text { Network semantics }
\end{aligned}
$$

From this we obtain an expression for $P\left(t \mid a, \neg f_{A}, \neg f_{G}\right)$ by normalization, i.e., $1 / \alpha$ is the sum of the two probability expressions:

$$
\frac{P\left(g \mid \neg f_{G}, t\right) P\left(\neg f_{G} \mid t\right) P(t)}{P\left(g \mid \neg f_{G}, t\right) P\left(\neg f_{G} \mid t\right) P(t)+P\left(g \mid \neg f_{G}, \neg t\right) P\left(\neg f_{G} \mid \neg t\right) P(\neg t)}
$$

which could also be rewritten as

$$
\frac{1}{1+\frac{P\left(g \mid \neg f_{G}, \neg t\right) P\left(\neg f_{G} \mid \neg t\right) P(\neg t)}{P\left(g \mid \neg f_{G}, t\right) P\left(\neg f_{G} \mid t\right) P(t)}} .
$$

If we substitute the known known probability values from the CPTs given above and extend the resulting fraction by $x$, we obtain

$$
\frac{x}{x+(1-x) \frac{P\left(\neg f_{G} \mid-t\right) P(\neg t)}{P\left(\neg f_{G} \mid t\right) P(t)}} .
$$

