

## DECISION METHODS FOR CTL AND LTL

1. Tableau method for CTL
2. Deciding satisfiability and validity in CTL and LTL

E. A. Emerson: *Automated Temporal Reasoning about Reactive Systems*, Section 4 (pp. 18–23).

## Key Decision Techniques

- Tableau method (for example CTL):
  - (i) Given a CTL formula, a tableau graph is built representing (essentially) all possible models of the formula.
  - (ii) The tableau is pruned and checked whether it represents any model of the formula.
- Automata theory methods (for example LTL):
  - (i) Given an LTL formula, a finite state (Büchi-) automaton is constructed accepting infinite words (paths) such that the automaton accepts (essentially) all possible full paths satisfying the formula.
  - (ii) Then it is checked whether the language accepted by the automaton is empty.

## Background

- Temporal logics CTL and LTL are decidable because they satisfy the finite model property (and there is an upper bound on the size of a counter-model).
- More efficient decision methods can be developed using tableau techniques and automata theory.

## 1. Tableau Method for CTL

- A CTL tableau is a bipartite graph where nodes are sets of formulas and of two types: OR-nodes and AND-nodes.
- For a CTL formula  $P$  a tableau is constructed by first transforming  $P$  to the *positive normal form* (where negations can appear only in front of atomic propositions) and then proceeding in two stages:
  - (i) building an initial tableau  $T_0$  and
  - (ii) reducing  $T_0$  to the final tableau  $T_1$  using pruning rules.
- In the positive normal form propositional connectives  $\wedge$ ,  $\vee$  are used and negation  $\neg$  appears only in front of atomic propositions.
- We denote by  $\sim P$  the formula  $\neg P$  in the positive normal form.

**Transformation Rules**

A CTL formula  $P$  can be transformed to the **positive normal form** using the following rules:

$$\begin{array}{ll}
 P \rightarrow Q & \mapsto \neg P \vee Q & \neg \mathbf{A}(PUQ) & \mapsto \mathbf{E}(\neg PBQ) \\
 \neg(P \vee Q) & \mapsto \neg P \wedge \neg Q & \neg \mathbf{E}(PUQ) & \mapsto \mathbf{A}(\neg PBQ) \\
 \neg(P \wedge Q) & \mapsto \neg P \vee \neg Q & \neg \mathbf{A}(PBQ) & \mapsto \mathbf{E}(\neg PUQ) \\
 \neg \neg P & \mapsto P & \neg \mathbf{E}(PBQ) & \mapsto \mathbf{A}(\neg PUQ) \\
 \neg \mathbf{AG}P & \mapsto \mathbf{EF}\neg P & & \\
 \neg \mathbf{E}FP & \mapsto \mathbf{AG}\neg P & \text{Note the shorthands:} & \\
 \neg \mathbf{EG}P & \mapsto \mathbf{AF}\neg P & \mathbf{A}(PBQ) : & \neg \mathbf{E}((\neg P)UQ) \\
 \neg \mathbf{AFP} & \mapsto \mathbf{EG}\neg P & \mathbf{E}(PBQ) : & \neg \mathbf{A}((\neg P)UQ) \\
 \neg \mathbf{AX}P & \mapsto \mathbf{EX}\neg P & & \\
 \neg \mathbf{EXP} & \mapsto \mathbf{AX}\neg P & & 
 \end{array}$$

**Building the Initial Tableau  $T_0$** 

- Given a CTL formula  $P$  we start with the OR-node  $D_0 = \{P\}$ .
- The successors of an OR-node  $D$  are AND-nodes obtained by applying  $\alpha/\beta$ -rules to the node  $D$ .
- The successors of an AND-node  $C$  are OR-nodes obtained by applying the *successor rule* to  $C$ .

**Remark.** If a successor  $C$  of an OR-node  $D$  already appears in the tableau, another copy of  $C$  is not introduced in the tableau but the successor of  $D$  is set to be the already existing node (and similarly for the successors of AND-nodes).

$\Rightarrow$  The tableau remains finite.

**Example**

Constructing the positive normal form  $\sim \mathbf{AG}(R \rightarrow (\neg Q \wedge \mathbf{A}(PUQ)))$ :

$$\begin{array}{l}
 \neg \mathbf{AG}(R \rightarrow (\neg Q \wedge \mathbf{A}(PUQ))) \\
 \mapsto \mathbf{EF}\neg(\neg R \vee (\neg Q \wedge \mathbf{A}(PUQ))) \\
 \mapsto \mathbf{EF}(R \wedge \neg(\neg Q \wedge \mathbf{A}(PUQ))) \\
 \mapsto \mathbf{EF}(R \wedge (Q \vee \neg \mathbf{A}(PUQ))) \\
 \mapsto \mathbf{EF}(R \wedge (Q \vee \mathbf{E}(\neg PBQ)))
 \end{array}$$

**Successors of an OR-Node**

Each successor of an OR-node  $D$  is a smallest set of formulas  $C$  such that  $D \subseteq C$  and  $C$  is **downward closed** under the  $\alpha$  and  $\beta$  rules below such that

- if  $\alpha \in C$ , then  $\alpha_1 \in C$  and  $\alpha_2 \in C$ ;
- if  $\beta \in C$ , then  $\beta_1 \in C$  or  $\beta_2 \in C$ .

$\alpha$  rules:

$P \wedge Q$	$\mathbf{AG}P$	$\mathbf{EG}P$
$P$	$P$	$P$
$Q$	$\mathbf{AXAG}P$	$\mathbf{EXEG}P$
$\mathbf{A}(PBQ)$	$\mathbf{E}(PBQ)$	
$\sim Q$	$\sim Q$	
$P \vee \mathbf{AXA}(PBQ)$	$P \vee \mathbf{EXE}(PBQ)$	

### Successors of an OR-Node—cont'd

$\beta$  rules:

$$\frac{P \vee Q}{P \mid Q} \qquad \frac{AFP}{P \mid \mathbf{AXAFP}} \qquad \frac{EFP}{P \mid \mathbf{EXEFP}}$$

$$\frac{\mathbf{A}(PUQ)}{Q \mid P \wedge \mathbf{AXA}(PUQ)} \qquad \frac{\mathbf{E}(PUQ)}{Q \mid P \wedge \mathbf{EXE}(PUQ)}$$

**Remark.** For literals and for formulas of the form  $\mathbf{AXP}$  and  $\mathbf{EXP}$  there are no applicable rules (and the expansion of a successor  $C$  ends in such formulas).

### Successors of AND-Nodes

The successors of an AND-node  $C$  are obtained with the *successor rule*:

- Let the set of formulas  $C$  contain the following  $\mathbf{AXP}_i/\mathbf{EXQ}_j$  formulas:

$$\mathbf{AXP}_1, \dots, \mathbf{AXP}_l \text{ and } \mathbf{EXQ}_1, \dots, \mathbf{EXQ}_k.$$

Then the successors of  $C$  are

$$D_1 = \{P_1, \dots, P_l, Q_1\}, \dots, D_k = \{P_1, \dots, P_l, Q_k\}.$$

- If the set  $C$  has no formulas of the form  $\mathbf{EXQ}_i$ , then  $C$  has a unique successor  $\{P_1, \dots, P_l\}$ .

Note that there is always at least one successor (which is the empty set if there are no formulas of the form  $\mathbf{AXP}_i$  either).

**Example.** The node

$$C = \{\mathbf{A}(PUQ), \mathbf{AXA}(PUQ), \mathbf{EGP}, P, \mathbf{EXEGP}, \mathbf{EFQ}, \mathbf{EXEFQ}\}.$$

has successors  $D_1 = \{\mathbf{A}(PUQ), \mathbf{EGP}\}$  and  $D_2 = \{\mathbf{A}(PUQ), \mathbf{EFQ}\}$ .

### Example

From the set  $D = \{\mathbf{AFEF}((P \wedge Q) \vee R)\}$  we can construct the following downward closed sets of formulas:

$$C_1 = \{\mathbf{AFEF}((P \wedge Q) \vee R), \mathbf{EF}((P \wedge Q) \vee R), (P \wedge Q) \vee R, P \wedge Q, P, Q\}$$

$$C_2 = \{\mathbf{AFEF}((P \wedge Q) \vee R), \mathbf{EF}((P \wedge Q) \vee R), (P \wedge Q) \vee R, R\}$$

$$C_3 = \{\mathbf{AFEF}((P \wedge Q) \vee R), \mathbf{EF}((P \wedge Q) \vee R), \mathbf{EXEF}((P \wedge Q) \vee R)\}$$

$$C_4 = \{\mathbf{AFEF}((P \wedge Q) \vee R), \mathbf{AXAFEF}((P \wedge Q) \vee R)\}$$

**Remark.** Downward closed sets of formulas for a node  $D$  can be built by constructing a tableau where the formulas in  $D$  are put to the root of the tableau and then  $\alpha$  and  $\beta$  rules are applied as in the tableau method for propositional logic. Each branch of the resulting tableau corresponds to a downward closed set.

### Pruning Rules

The final tableau is obtained by pruning the initial tableau  $T_0$  using the following rules until none of them is applicable.

- Remove an AND-node containing a formula and its negation.
- Remove an AND-node if one of its original successors have been removed.
- Remove an OR-node if all its original successors have been removed.
- Remove an AND-node if it contains a **eventuality formula** not satisfiable in the current tableau.

Eventuality formulas are of the form:

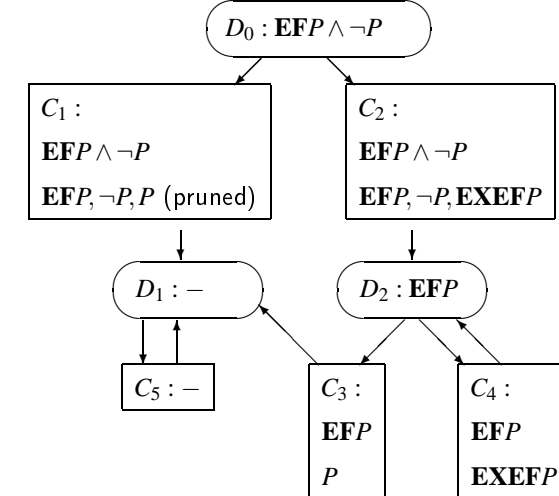
$$\mathbf{E}(PUQ), \mathbf{EFQ}, \mathbf{A}(PUQ) \text{ and } \mathbf{AFQ}.$$

### Satisfiability of Eventuality Formulas

- An eventuality formula  $\mathbf{EF}Q$  ( $\mathbf{E}(PUQ)$ ) is satisfiable in an AND-node  $C$  iff the tableau includes a path from  $C$  to an AND-node  $C'$  containing the formula  $Q$  (and all other AND-nodes in the path contain the formula  $P$ ).
- An eventuality formula  $\mathbf{AF}Q$  ( $\mathbf{A}(PUQ)$ ) is satisfiable in an AND-node  $C$  iff there is a finite acyclic subgraph in the tableau such that
  - (i) The root of the subgraph is the node  $C$ .
  - (ii) For each interior OR-node in the subgraph exactly one of its successor AND-nodes in the current tableau is in the subgraph.
  - (iii) For each interior AND-node all of its successor OR-nodes in the current tableau are in the subgraph.
  - (iv) Every leaf node of the subgraph is an AND-node containing the formula  $Q$  (and all other AND-nodes contain  $P$ ).

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### The Tableau as a Graph



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### Example

- The node  $D_0 = \{\mathbf{EFP} \wedge \neg P\}$  has AND-successors  $C_1 = \{\mathbf{EFP} \wedge \neg P, \mathbf{EFP}, \neg P, P\}$  and  $C_2 = \{\mathbf{EFP} \wedge \neg P, \mathbf{EFP}, \neg P, \mathbf{EXEFP}\}$ .
- The OR-successors of  $C_1$ :  $D_1 = \{-\}$ .  
The OR-successors of  $C_2$ :  $D_2 = \{\mathbf{EFP}\}$ .
- The AND-successors of  $D_2$ :  $C_3 = \{\mathbf{EFP}, P\}$  and  $C_4 = \{\mathbf{EFP}, \mathbf{EXEFP}\}$ .  
The AND-successors of  $D_1$ :  $C_5 = \{-\}$ .
- The OR-successors of  $C_3$  and  $C_5$ :  $\{-\} = D_1$ .  
The OR-successors of  $C_4$ :  $\{\mathbf{EFP}\} = D_2$ .
- Initial tableau  $T_0$  is now finished.
- Pruning: Remove  $C_1$  (contains a formula and its negations). Final tableau  $T_1$  now ready (an eventuality formula  $\mathbf{EFP}$  satisfiable in AND-nodes  $C_2, C_3, C_4$ ).

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## 2. Deciding Satisfiability and Validity in CTL and LTL

- The final tableau  $T_1$  for a CTL formula  $P$  provides a model for  $P$  in case  $P$  is satisfiable.
- The validity of a CTL formula  $P$  can be determined by checking whether the formula  $\sim P$  is unsatisfiable.
- The satisfiability/validity of an LTL formula  $P$  can be reduced to the satisfiability/validity of a CTL formula.

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### Deciding CTL Satisfiability using Tableaux

**Theorem.** Let  $P$  be a CTL formula in the positive normal form. Then  $P$  is satisfiable iff the final tableau  $T_1$  for  $P$  has an AND-node containing  $P$ .

A tableau provides a satisfying model for a CTL formula  $P$ :

- The states of the model are given by the AND-nodes and the valuation is given by the atomic propositions in the AND-nodes.
- The model must contain at least one AND-node containing  $P$ .
- The successors need to be chosen such that the model is serial and for all AND-nodes the eventuality formulas in the AND-nodes are satisfiable.

**Remark.** The tableau method can be used for program synthesis (to construct program control skeletons):

- The specification of the program is provided as a CTL formula.
- The method is used to construct a model satisfying the specification (providing the control skeleton).

### Deciding CTL Validity using Tableaux

- A formula  $\varphi$  is valid iff its negation  $\neg\varphi$  is not satisfiable.
- Satisfiability can be determined using the tableau method:
  - transform the formula  $\neg\varphi$  to the positive normal form  $\sim\varphi$ ;
  - construct a tableau for the formula  $\sim\varphi$ .
- Hence, a CTL formula  $\varphi$  is valid iff  $\sim\varphi$  is not satisfiable iff in the final tableau for the formula  $\sim\varphi$  there is no AND-node containing the formula  $\sim\varphi$ .

### Example

For a CTL formula  $\mathbf{EFP} \wedge \neg P$  we can construct a model  $\langle S, R, v \rangle$  from the tableaux  $T_1$  as follows:

- Let  $S = \{C_2, C_3, C_5\}$ ,  $R = \{\langle C_2, C_3 \rangle, \langle C_3, C_5 \rangle, \langle C_5, C_5 \rangle\}$  and  $v(P, s) = \text{true}$  if  $s = C_3$  and otherwise  $v(P, s) = \text{false}$ .
- Another possibility:  
 $S = \{C_2, C_3, C_4, C_5\}$ ,  $R = \{\langle C_2, C_4 \rangle, \langle C_4, C_3 \rangle, \langle C_3, C_5 \rangle, \langle C_5, C_5 \rangle\}$   
 and  $v(P, s) = \text{true}$  if  $s = C_3$  and otherwise  $v(P, s) = \text{false}$ .

**Remark.** Consider a model

$S = \{C_2, C_4\}$ ,  $R = \{\langle C_2, C_4 \rangle, \langle C_4, C_4 \rangle\}$  and  $v(P, C_2) = v(P, C_4) = \text{false}$ .

This is not a satisfying model because the eventuality formula  $\mathbf{EFP}$  in  $C_2$  and  $C_4$  is not satisfiable.

### Example

Is a CTL formula

$$\varphi = \mathbf{EX}(P \vee Q) \rightarrow (\mathbf{EXP} \vee \mathbf{EX}Q)$$

valid?

Transform  $\neg\varphi$  to the positive normal form  $\sim\varphi$ :

$$\neg(\mathbf{EX}(P \vee Q) \rightarrow (\mathbf{EXP} \vee \mathbf{EX}Q))$$

$$\mapsto \mathbf{EX}(P \vee Q) \wedge \neg(\mathbf{EXP} \vee \mathbf{EX}Q)$$

$$\mapsto \mathbf{EX}(P \vee Q) \wedge (\neg\mathbf{EXP} \wedge \neg\mathbf{EX}Q)$$

$$\mapsto \mathbf{EX}(P \vee Q) \wedge \mathbf{AX}\neg P \wedge \mathbf{AX}\neg Q$$

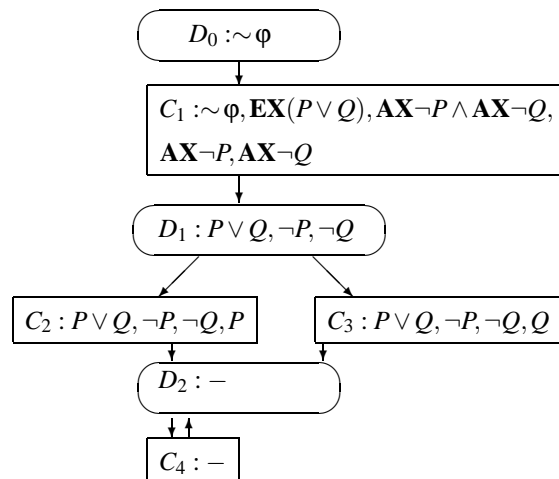
$$\text{Hence, } \sim\varphi = \mathbf{EX}(P \vee Q) \wedge \mathbf{AX}\neg P \wedge \mathbf{AX}\neg Q.$$

**Example: AND- and OR-Successors**

- The AND-successors of the node  $D_0 = \{\sim\varphi\}$ :  
 $C_1 = \{\sim\varphi, \mathbf{EX}(P \vee Q), \mathbf{AX}\neg P \wedge \mathbf{AX}\neg Q, \mathbf{AX}\neg P, \mathbf{AX}\neg Q\}$ .
  - The OR-successor of  $C_1$ :  
 $D_1 = \{P \vee Q, \neg P, \neg Q\}$ .
  - The AND-successors of  $D_1$ :  
 $C_2 = D_1 \cup \{P\}$  and  $C_3 = D_1 \cup \{Q\}$ .
  - The OR-successors of  $C_2$ :  $D_3 = \{\}$ .  
 The OR-successors of  $C_3$ :  $\{\} = D_3$ .  
 The AND-successors of  $D_3$ :  $C_4 = \{\}$ .  
 The OR-successors of  $C_4$ :  $\{\} = D_3$ .
- $\Rightarrow$  The initial tableau  $T_0$  is ready.

**Example: Pruning of the Initial Tableau**

1. Nodes  $C_2$  and  $C_3$  can be removed because they contain a formula and its negation.
  2. OR-node  $D_1$  can be removed (all successors removed).
  3. AND-node  $C_1$  can be removed (a successor removed).
  4. OR-node  $D_0$  can be removed (all successors removed).
- $\Rightarrow$  Final tableau  $T_1$  is ready.
- $T_1$  does not contain an AND-node which includes  $\sim\varphi$ .  
 Hence,  $\sim\varphi$  is not satisfiable and  $\varphi$  is valid.

**Example: The Initial Tableau****Deciding LTL Satisfiability using Tableaux**

- CTL tableaux can be used for deciding LTL satisfiability.

**Theorem.** Let  $P$  be an LTL formula in the positive normal form and let the CTL formula  $P'$  be obtained from  $P$  by replacing operators  $\mathbf{F}, \mathbf{G}, \mathbf{X}, \mathbf{U}, \mathbf{B}$  systematically by  $\mathbf{AF}, \mathbf{AG}, \mathbf{AX}, \mathbf{AU}, \mathbf{AB}$ , respectively.

Then  $P$  is satisfiable in LTL iff  $P'$  is satisfiable in CTL.

**Example.** An LTL formula  $\mathbf{G}(\neg \mathbf{PUQ})$  is satisfiable iff  $\mathbf{AGA}(\neg \mathbf{PUQ})$  is satisfiable (in CTL).



## Computational Complexity

- CTL  
Model checking: **P**-complete,  $O(|M| \cdot |P|)$   
Satisfiability: **EXPTIME**-complete
- LTL  
Model checking: **PSPACE**-complete,  $O(|M| \cdot \exp(|P|))$   
Satisfiability: **PSPACE**-complete
- CTL\*  
Model checking: **PSPACE**-complete,  $O(|M| \cdot \exp(|P|))$   
Satisfiability: **2EXPTIME**-complete



## Summary

- Methods for deciding satisfiability (and validity) in temporal logics are typically based on tableau techniques and automata theory.
- The tableau method for CTL can be seen as a systematic procedure to build a model for a formula (in positive normal form).
- In the tableau method first an initial tableau is built which is then reduced using pruning rules. If the reduced tableau satisfies a given condition, a model of the original formula can be obtained from the reduced tableau.
- The method can be used for synthesizing (control skeletons of) programs.
- Satisfiability of a LTL formula can be reduced to satisfiability of a CTL formula and, hence, the CTL tableau method can be used for deciding satisfiability (and validity) in LTL.



## Restricted Subclasses

- Satisfiability can be decided in polynomial time, for instance, in subclasses which are interesting for program synthesis.
- For example SCTL (Simplified CTL):  

$$P_1 \vee \dots \vee P_n, \mathbf{AG}(P_1 \vee \dots \vee P_n)$$

$$\mathbf{AG}(P_0 \rightarrow \mathbf{AF}(P_1 \vee \dots \vee P_n)),$$

$$\mathbf{AG}(P_0 \rightarrow \mathbf{A}(P_1 \vee \dots \vee P_n \mathbf{U} Q_1 \vee \dots \vee Q_m))$$

$$\mathbf{AG}(P_0 \rightarrow \mathbf{AX}(P_1 \vee \dots \vee P_n) \wedge \mathbf{EX}(Q_1 \vee \dots \vee Q_m) \wedge \dots \wedge \mathbf{EX}(R_1 \vee \dots \vee R_l))$$
 where  $P_i, Q_i, R_i$  atomic propositions such that the **ESC-assumption** holds (eventualities are "history-free").
- For example, RLTL (Restricted LTL)  

$$\mathbf{G}(P_1 \vee \dots \vee P_n)$$

$$\mathbf{G}(P_0 \rightarrow \mathbf{F}(P_1 \vee \dots \vee P_n))$$

$$\mathbf{G}(P_0 \rightarrow \mathbf{X}(P_1 \vee \dots \vee P_n))$$
 where each  $P_i$  is an atomic proposition.