

Synchronous Computations, Basic techniques (Secs. 6.1-6.2)

T-79.4001 Seminar on Theoretical Computer Science

Alexi Hänninen

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Outline

Synchronous Systems

- Definitions

- New Restrictions

Synchronous Algorithms

- Speed

- TwoBits

- The Cost of Synchronous Protocols

Communicators, pipeline, and transformers

- Two-Party Communication Problem

- Pipeline

- Asynchronous-to-Synchronous Transformation

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Notation

- ▶ n is the number of nodes, m is the number of edges
- ▶ Standard set of restrictions
 $\mathbf{R} = \{Bidirectional\ Links, Connectivity, Total\ Reliability\}$
- ▶ $\mathbf{M}[P]$ is the number of messages needed in protocol P
- ▶ $\mathbf{T}[P]$ is the time required in protocol P
- ▶ $\mathbf{B}[P]$ is the number of bits needed in protocol P
- ▶ $\langle \mathbf{T}, \mathbf{B} \rangle$ is the total cost of protocol

Restrictions for fully synchronous system

6.1.1. Synchronized Clocks

- ▶ All entities have a clock, which are incremented by one unit δ simultaneously. Clocks are not necessarily at the same time.
- ▶ All messages are transmitted to their neighbors only at the strike of a clock tick
- ▶ At each clock tick, an entity will send at most one message to the same neighbor

6.1.2 Bounded Communication Delays

- ▶ There exists a known upper bound on the communication delays Δ

System which satisfies these is a fully synchronous system.
The messages are called packets, and have a bounded size c .

Synchronous restriction: **Synch**

Every synchronous system with 6.1.1. and 6.1.2 can be “normalized” so that a communication delay is one new tick δ (assuming that entities know the time when to begin ticking)

6.1.3 Unitary Communication Delays

- ▶ In absence of failures, a transmitted message will arrive and be processed after at most one clock tick

6.1.1 + 6.1.3. = **Synch**

- ▶ Messages sent in time t is received at time $t + 1$
- ▶ Simplifies situation

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Synchronous Minimum Finding

AsFar + delay in send = **Speed**

- ▶ **IR** \cup **Synch** \cup *Ring* \cup *InputSize*(2^c)
- ▶ **AsFar**: Optimal message complexity on average but worst-case is $\mathcal{O}(n^2)$.
- ▶ Idea: Delay forwarding messages with large id to allow smaller id messages catch it up.
- ▶ Delay is $f(i)$ which is monotonical
- ▶ Correctness: Basically because **AsFar** is (message with smallest id is newer trashed)

Complexity

If $f(i) := 2^i$

$$\mathbf{M}[\text{Speed}] = \sum_{j=1}^n \frac{n}{2^{j-1}} < 2n$$

In the time when first has went through, second largest has went at most half the way, third largest $n/4 \dots$

$$\mathbf{M}[\text{Speed}] = \mathcal{O}(n)!$$

- ▶ Message complexity smaller than the $\mathcal{O}(n \log(n))$ lower bound of asynchronous rings
- ▶ However, $\mathbf{T}[\text{Speed}] = \mathcal{O}(n2^i)$
- ▶ Exponential to the input values, worse than to size n .

TwoBits

- ▶ Situation: x wants to send bits α to his neighbor y with only two bits.
- ▶ $Int(1\alpha)$ is some known bijection between bit strings and integers.
- ▶ Silence is information also!

1. Entity

1. Send “start counting”
2. Wait $\text{Int}(1\alpha)$ ticks
3. Send “stop counting”

2. Entity

1. Upon receiving “start counting”, record current time c_1
2. When “stop counting” is received, calculate the difference of current time c_2 and c_1 and use the fact that $c_2 - c_1 = \text{Int}(1\alpha)$, from which the α can be deduced.

Total Cost

- ▶ The cost of a fully synchronous protocol is both time and transmissions.
- ▶ Time can be saved by using more bits, and bits can be saved by using more time.

$$\text{Cost} [\textit{Protocol } P] = \langle \mathbf{B} [P], \mathbf{T} [P] \rangle$$

$$\text{Cost} [\textit{Speed}(\mathbf{i})] = \langle \mathcal{O}(n \log(\mathbf{i})), \mathcal{O}(n2^{\mathbf{i}}) \rangle$$

$$\text{Cost} [\textit{TwoBits}(\alpha)] = \langle 2, \mathcal{O}(2^{|\alpha|}) \rangle$$

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Two-Party Communication Problem **TPC**

- ▶ In fully synchronous systems, also the absence of transmission can be used to convey information between the nodes.
- ▶ There are many solutions to the Two-Party Communication Problem, called *communicators*.
- ▶ Time and bit cost of sending information I between neighbours using C are denoted $Time(C, I)$ and $Bit(C, I)$, respectively.

TPC settings

- ▶ *Sender* will send k packets which defines $k - 1$ quanta of time q_1, \dots, q_{k-1} .
- ▶ The ordered sequence $\langle p_0 : \mathbf{q}_1 : \dots : \mathbf{q}_{k-1} : p_{k-1} \rangle$ is called a communication sequence.
- ▶ A protocol *communicator* C must specify an encoding function which encodes information to a communication sequence and a decoding function to decode it.

2-bit Communicator Protocol \mathcal{C}_2

- ▶ $encode(\mathbf{i}) = \langle b_0 : \mathbf{i} : b_1 \rangle$
- ▶ $decode(b_0 : \mathbf{q}_1 : b_1) = \mathbf{q}_1$
- ▶ $Cost[\mathcal{C}_2(\mathbf{i})] = \langle 2, \mathbf{i} + 2 \rangle$

Hacking

- ▶ The values of bits are not used, so they can be changed. The protocol is *corruption tolerant*.
- ▶ We can also encode 2 bits to the values of b_0 and b_1 . The new protocol is called $\mathcal{R}_2(\mathbf{i})$ and the time reduces to $2 + \frac{i}{4}$.
- ▶ From now on, we restrict ourselves to corruption tolerant TPC, and denote the communication sequence with only the quantas \mathbf{q}_i as a tuple $\langle \mathbf{q}_1 : \dots : \mathbf{q}_k \rangle$

3-bit Communicators

- ▶ $encode(\mathbf{i}) = \langle \lfloor \sqrt{\mathbf{i}} \rfloor : \mathbf{i} - (\lfloor \sqrt{\mathbf{i}} \rfloor)^2 \rangle$.
- ▶ $decode(\mathbf{q}_1 : \mathbf{q}_2) = \mathbf{q}_1^2 + \mathbf{q}_2$.
- ▶ $Cost [C_2(\mathbf{i})] = \langle 3, 3 + \lfloor \sqrt{\mathbf{i}} \rfloor \rangle$, sublinear!.

$(2^d + 1)$ -bit Communicators

- ▶ The idea can be quite easily extended using this idea with divide and conquer.
- ▶ A solution protocol using $k = 2^d + 1$ bits will use $\mathcal{O}(i^{\frac{1}{k}})$ time and k bits.

Pipeline - a setting

- ▶ Consider now the case where the two communicators x and y are not neighbours.
- ▶ However, a chain x_1, x_2, \dots, x_p , where $x_1 = x$ and $x_p = y$, is known to everybody.
- ▶ If the information I is sent from x_i to x_{i+1} using always a Communicator C between them, the time cost is $(p - 1)Time(C, I)$.

Pipeline - a solution

- ▶ To reduce the amount of time, we can form a *pipeline*.
- ▶ Once a relayer x_i , $i \in \{2, \dots, p - 1\}$, gets a message, it will forward it in the next tick.
- ▶ The time cost is reduced to $(p - 1) + \text{Time}(C, I)$
- ▶ The bit cost is $(p - 1)\text{Bit}(C, I)$ for both.

Computing in Pipeline

- ▶ Also computations can be performed in a pipeline.
- ▶ Consider a maximum finding in pipeline, using **TwoBits** as our communicator. All entities x_j has an integer of information I_j .
- ▶ The sender x_1 will send first “start” message and after I_1 tick “stop” message.
- ▶ All x_j will forward the “start” message without delay. When the “stop” message is received, it is forwarded unless the time between “start” and “stop” is less than I_j . In this case the “stop” is delayed accordingly.

Computing in Pipeline

- ▶ Number of bits is $(p - 1)Bits(C, I_{max})$, same as without pipeline.
- ▶ Time is reduced to $(p - 1) + Time(C, I_{max})$.
- ▶ Only restriction for C :
“If $I > J$, then in C the communication sequence for I is lexicographically smaller than for J .” (from the book)

Asynchronous-to-Synchronous Transformation

- ▶ If A is a known solution to some problem in asynchronous setting, it does not depend of the timing conditions.
- ▶ The maximum size $m(A)$ of the messages used by A must be less than the packet size c , otherwise the message complexity is increased.
- ▶ A can also be automatically converted to fit in synchronous system just by using a transformer.

Transformers

- ▶ *Transformer* $\tau [C]$ Given any asynchronous protocol A , replace the asynchronous transmission-reception of each message in A by the communication, using C , of the information contained in that message.

Transformers

- ▶ $M(A)$ message complexity of A
- ▶ $m(A)$ size of the largest message
- ▶ T_{causal} the length of the longest chain of communication, $\leq M(A)$
- ▶ **Lemma 6.2.2 Transformation Lemma**
 $Cost[\tau[C](A)] \leq \langle M(A)Packets(C, m(A)), T_{causal}(A)Time(C, 2^{m(A)}) \rangle$

An Example

- ▶ Election in a Synchronous Ring using Stages and a transformer \rightarrow *SynchStages*.
- ▶ *SynchStages* uses $\mathcal{O}(n \log n)$ bits and $\mathcal{O}(in \log n)$ time
- ▶ Better than the cost of time $\mathcal{O}(n \log i)$ and packets $\mathcal{O}(in2^i)$ of the **Speed**.

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