Part I

Markov Chains and Stochastic Sampling

1 Markov Chains and Random Walks on Graphs

1.1 Structure of Finite Markov Chains

We shall only consider Markov chains with a finite, but usually very large, state space $S = \{1, \ldots, n\}$.

An $S$-valued (discrete-time) stochastic process is a sequence $X_0, X_1, X_2, \ldots$ of $S$-valued random variables over some probability space $\Omega$, i.e. a sequence of (measurable) maps $X_t : \Omega \to S, t = 0, 1, 2, \ldots$.

Such a process is a Markov chain if for all $t \geq 0$ and any $i_0, i_1, \ldots, i_{t-1}, i, j \in S$ the following “memoryless” (forgetting) condition holds:

$$
\Pr(X_{t+1} = j \mid X_0 = i_0, X_1 = i_1, \ldots, X_{t-1} = i_{t-1}, X_t = i) = \Pr(X_{t+1} = j \mid X_t = i).
$$

Consequently, the process can be described completely by giving its initial distribution (vector)$^1$

$$
p^0 = [p_1^0, \ldots, p_n^0] = [p_i^0]_{i=1}^n, \text{ where } p_i^0 = \Pr(X_0 = i)
$$

$^1$By a somewhat confusing convention, distributions in Markov chain theory are represented as row vectors. We shall be denoting the $1 \times n$ column vector with components $p_1, \ldots, p_n$ as $(p_1, \ldots, p_n)$, and the corresponding $n \times 1$ row vector as $[p_1, \ldots, p_n] = (p_1, \ldots, p_n)^T$. All vectors shall be column vectors unless otherwise indicated by text or notation.
and its sequence of transition (probability) matrices

\[ P^{(t)} = \left( p_{ij}^{(t)} \right)_{i,j=1}^n, \quad \text{where } p_{ij}^{(t)} = \Pr(X_t = j \mid X_{t-1} = i). \]

Clearly, under condition (1), the distribution vector at time \( t \geq 1 \)

\[ p^{(t)} = \left[ \Pr(X_t = j) \right]_{j=1}^n \]

is obtained from \( p^{(k-1)} \) simply by computing for each \( j \):

\[ p_j^{(t)} = \sum_{i=1}^n p_i^{(t-1)} \cdot p_{ij}, \]

or more compactly

\[ p^{(t)} = p^{(t-1)} P^{(t)}. \]

Recurring back to the initial distribution, this yields

\[ p^{(t)} = p^0 P^{(1)} P^{(2)} \ldots P^{(t)}. \] (2)

If the transition matrix is time-independent, i.e. \( P^{(t)} = P \) for all \( t \geq 1 \), the Markov chain is homogeneous, otherwise inhomogeneous. We shall be mostly concerned with the homogeneous case, in which formula (2) simplifies to

\[ p^{(t)} = p^0 P^t. \]

We shall say in general that a vector \( q \in \mathbb{R}^n \) is a stochastic vector if it satisfies

\[ q_i \geq 0 \quad \forall \ i = 1, \ldots, n \quad \text{and} \quad \sum_i q_i = 1. \]

A matrix \( Q \in \mathbb{R}^{n \times n} \) is a stochastic matrix if all its row vectors are stochastic vectors.

Now let us assume momentarily that for a given homogeneous Markov Chain with transition matrix \( P \) and initial probability distribution \( p^0 \) there exists a limit distribution \( \pi \in [0, 1]^n \) such that

\[ \lim_{k \to \infty} p_i^{(t)} = \pi \quad \text{(in any norm, e.g. coordinatewise).} \] (3)

Then it must be the case that

\[ \pi = \lim_{t \to \infty} p^0 P^t = \lim_{t \to \infty} p^0 P^{t+1} = \left( \lim_{t \to \infty} p^0 P^t \right) P = \pi P. \]
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Figure 1: A Markov chain for Helsinki weather.

Thus, any limit distribution satisfying property (3), if such exist, is a left eigenvector of the transition matrix with eigenvalue 1, and can be computed by solving the equation $\pi = \pi P$. Solutions to this equation are called the equilibrium or stationary distributions of the chain.

**Example 1.1** The weather in Helsinki. Let us say that tomorrow’s weather is conditioned on today’s weather as represented in Figure 1 or in the transition matrix:

$$
P = \begin{bmatrix} 0.6 & 0.4 \\ 0.3 & 0.7 \end{bmatrix}
$$

Then the long-term weather distribution can be determined uniquely, and in fact independent of the initial conditions, by solving

$$
\pi P = \pi, \quad \sum_i \pi_i = 1
$$

$$
\iff \begin{bmatrix} \pi_r & \pi_s \end{bmatrix} \begin{bmatrix} 0.6 & 0.4 \\ 0.7 & 0.3 \end{bmatrix} = \begin{bmatrix} \pi_r & \pi_s \end{bmatrix}, \quad \pi_r + \pi_s = 1
$$

$$
\iff \begin{cases} 
\pi_r = 0.6\pi_r + 0.7\pi_s, \\
\pi_s = 0.4\pi_r + 0.3\pi_s, \\
\pi_r + \pi_s = 1 
\end{cases}
$$

$$
\iff \begin{cases} 
\pi_r = 0.64 \\
\pi_s = 0.36 
\end{cases}
$$

Every finite Markov chain has at least one stationary distribution, but as the following examples show, this need not be unique, and even if it is, then the chain does not need to converge towards it in the sense of equation (3).

**Example 1.2** A reducible Markov chain. Consider the chain represented in Figure 2. Clearly any distribution $p = [p_1 \quad p_2]$ is stationary for this chain. The cause
for the existence of several stationary distributions is that the chain is reducible, meaning that it consists of several “noncommunicating” components. (Precise definitions are given below.)

Any irreducible ("fully communicating") chain has a unique stationary distribution, but this does not yet guarantee convergence in the sense of equation (3).

**Example 1.3 Periodic Markov chains.** Consider the chains represented in Figure 3. These chains are periodic, with periods 2 and 3. While they do have unique stationary distributions indicated in the figure, they only converge to those distributions from the corresponding initial distributions; otherwise probability mass "cycles" through each chain.

So when is a unique stationary limit distribution guaranteed? The brief answer is as follows.

Consider a finite, homogeneous Markov chain with state set $S$ and transition matrix $P$. The chain is:

(i) **irreducible**, if any state can be reached from any other state with positive probability, i.e.

$$ \forall i, j \in S \ \exists t \geq 0 : P_{ij}^t > 0; $$
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(ii) aperiodic if for any state \( i \in S \) the greatest common divisor of its possible recurrence times is 1, i.e. denoting

\[
N_i = \{ t \geq 1 : P^t_{ii} > 0 \}
\]

we have \( \gcd(N_i) = 1 \), \( \forall i \in S \).

**Theorem (Markov Chain Convergence)** A finite homogeneous Markov chain that is irreducible and aperiodic has a unique stationary distribution \( \pi \), and the chain will converge towards this distribution from any initial distribution \( p^0 \) in the sense of Equation (3). \( \square \)

Irreducible and aperiodic chains are also called regular or ergodic.

We shall prove this important theorem below, establishing first the existence and uniqueness of the stationary distribution, and then convergence. Before going into the proof, let us nevertheless first look into the structure of arbitrary, possibly nonregular, finite Markov chains somewhat more closely.

Let the finite state space be \( S \) and the homogeneous transition matrix be \( P \).

A set of states \( C \subseteq S, C \neq \emptyset \) is closed or invariant, if \( p_{ij} = 0 \) \( \forall i \in C, j \notin C \).

A singleton closed state is absorbing (i.e. \( p_{ii} = 1 \)).

A chain is irreducible if \( S \) is the only closed set of states. (This definition can be seen to be equivalent to the one given earlier.)

**Lemma 1.1** Every closed set contains a minimal closed set as a subset. \( \square \)

State \( j \) is reachable from state \( i \), denoted \( i \rightarrow j \), if \( P^t_{ij} > 0 \) for some \( t \geq 0 \).

States \( i, j \in S \) communicate, denoted \( i \leftrightarrow j \), if \( i \rightarrow j \) and \( j \rightarrow i \).

**Lemma 1.2** The communication relation \( \leftrightarrow \) is an equivalence relation. All the minimal closed sets of the chain are equivalence classes with respect to \( \leftrightarrow \). The chain is irreducible if and only if all its states communicate. \( \square \)

States which do not belong to any of the minimal closed subsets are called transient.

One may thus partition the chain into equivalence class with respect to \( \leftrightarrow \). Each class is either a minimal closed set or consists of transient states. This is illustrated in Figure 4. By “reducing” the chain in this way one obtains a DAG-like structure, with the minimal closed sets as leaves and the transient components as internal nodes. (Actually a “forest” if the chain is disconnected.) An irreducible chain of course reduces to a single node.
The period of state \( i \in S \) is
\[
gcd\{k \mid P_{ii}^k > 0\}.
\]

A state with period 1 is aperiodic.

**Lemma 1.3** Two communicating states have the same period. Hence, every component of the “\( \leftrightarrow \)” relation has a uniquely determined period. \( \square \)

Define the first hit (or first passage) probabilities for states \( i \to j \) and \( t \geq 1 \) as:
\[
f_{ij}^{(t)} = \Pr(X_1 \neq j, X_2 \neq j, \ldots, X_{t-1} \neq j, X_t = j \mid X_0 = i),
\]
and the hitting (or passage) probability for \( i \to j \) as
\[
f_{ij}^* = \sum_{t \geq 1} f_{ij}^{(t)}.
\]

Then the expected hitting (passage) time for \( i \to j \) is
\[
\mu_{ij} = \begin{cases} 
\sum_{t \geq 1} t f_{ij}^{(t)}, & \text{if } f_{ij}^* = 1; \\
\infty & \text{if } f_{ij}^* < 1
\end{cases}
\]

For \( i = j \), \( \mu_{ii} \) is called the expected return time, and often denoted simply \( \mu_i \).

State \( i \in S \) is recurrent (or persistent) if \( f_{ii}^* = 1 \), otherwise it is transient. (In infinite Markov chains the recurrent states are further divided into positive recurrent...
with \( \mu_i < \infty \) and null recurrent with \( \mu_i = \infty \), but the latter case does not occur in finite Markov chains and thus need not concern us here.)

The following theorem provides an important characterisation of the recurrent states.

Notation: \( P^k = (p^{(k)}_{ij})_{i,j=1}^n \).

**Theorem 1.4** State \( i \in S \) is recurrent if and only if

\[
\sum_{k \geq 0} p^{(k)}_{ii} = \infty.
\]

Correspondingly, \( i \in S \) is transient if and only if

\[
\sum_{k \geq 0} p^{(k)}_{ii} < \infty.
\]

**Proof.** Recall the relevant definitions:

\[
\begin{align*}
p^{(k)}_{ii} &= \Pr(X_k = i \mid X_0 = i), \\
f^{(t)}_{ii} &= \Pr(X_1 \neq i, \ldots, X_{t-1} \neq i, X_t = i \mid X_0 = i).
\end{align*}
\]

Then it is fairly clear that

\[
 p^{(k)}_{ii} = \sum_{t=1}^k f^{(t)}_{ii} p^{(k-t)}_{ii} = \sum_{t=0}^{k-1} f^{(k-t)}_{ii} p^{(t)}_{ii}.
\]

Consequently, for any \( K \):

\[
\begin{align*}
\sum_{k=1}^K p^{(k)}_{ii} &= \sum_{k=1}^K \sum_{t=0}^{k-1} f^{(k-t)}_{ii} p^{(t)}_{ii} \\
&= \sum_{t=0}^{K-1} f^{(t)}_{ii} \sum_{k=t+1}^K p^{(k-t)}_{ii} \\
&\leq \sum_{t=0}^K f^{(t)}_{ii} f^*_{ii} \\
&= \left( 1 + \sum_{t=1}^K f^{(t)}_{ii} \right) f^*_{ii}
\end{align*}
\]

Since \( K \) was arbitrary, we obtain:

\[
(1 - f^*_{ii}) \sum_{k=1}^{\infty} p^{(k)}_{ii} \leq f^*_{ii}.
\]

Now if \( i \in S \) is transient, i.e. \( f^*_{ii} < 1 \), then

\[
\sum_{k \geq 1} p^{(k)}_{ii} \leq \frac{f^*_{ii}}{1 - f^*_{ii}} < \infty.
\]
Conversely, assume that \( i \in S \) is recurrent, i.e. \( f_{ii}^* = 1 \). Now one can see that
\[
\Pr(X_t = i \text{ for at least two } t \geq 1 \mid X_0 = i) = \sum_{t,t' \geq 1} f_{ii}^{(t)} f_{ii}^{(t')} = \left( \sum_{t \geq 1} f_{ii}^{(t)} \right)^2 = (f_{ii}^*)^2 = 1,
\]
and by induction that
\[
\Pr(X_t = i \text{ for at least } s \text{ times } \mid X_0 = i) = (f_{ii}^*)^s = 1.
\]
Consequently,
\[
P_{kk}^\infty \triangleq \Pr(X_k = i \text{ infinitely often } \mid X_0 = i) = \lim_{s \to \infty} (f_{ii}^*)^s = 1.
\]
However, if \( \sum_{k \geq 0} p_{ii}^{(k)} < \infty \), then by the Borel-Cantelli lemma (see below) it should be the case that \( p_{kk}^\infty = 0 \).

Thus it follows that if \( f_{ii}^* = 1 \), then also \( \sum_{k \geq 0} P_{ii}^{(k)} = \infty \). □

**Lemma (Borel-Cantelli, “easy case”)**

Let \( A_0,A_1,\ldots \) be events, and \( A \) the event “infinitely many of the \( A_k \) occur”. Then
\[
\sum_{k \geq 0} \Pr(A_k) < \infty \Rightarrow \Pr(A) = 0.
\]

**Proof.**

Clearly \( A = \bigcap_{m \geq 0} \bigcup_{k \geq m} A_k \). Thus for all \( m \geq 0 \),
\[
\Pr(A) \leq \Pr \left( \bigcup_{k \geq m} A_k \right) \leq \sum_{k \geq m} \Pr(A_k) \to 0 \text{ as } m \to \infty,
\]
assuming the sum \( \sum_{k \geq 0} \Pr(A_k) \) converges. □

Let \( C_1,\ldots,C_m \subseteq S \) be the minimal closed sets of a finite Markov chain, and \( T \triangleq S \setminus (C_1 \cup \cdots \cup C_m) \).

**Theorem 1.5** (i) Any state \( i \in C_r \), for some \( r = 1,\ldots,m \), is recurrent.
(ii) Any state \( i \in T \) is transient.
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Proof. (i) Assume \( i \in C, C \) minimal closed subset of \( S \). Then for any \( k \geq 1 \),

\[
\sum_{j \in S} p_{ij}^{(k)} = \sum_{j \in C} p_{ij}^{(k)} = 1
\]

because \( C \) is closed and \( P \) is a stochastic matrix. Consequently,

\[
\sum_{k \geq 0} \sum_{j \in C} p_{ij}^{(k)} = \infty,
\]

and because \( C \) is finite, there must be some \( j_0 \in C \) such that

\[
\sum_{k \geq 0} p_{ij_0}^{(k)} = \infty.
\]

Since \( j_0 \leftrightarrow i \), there is some \( k_0 \geq 0 \) such that \( p_{j_0i}^{(k_0)} = p_0 > 0 \). But then

\[
\sum_{k \geq 0} p_{ii}^{(k)} \leq \sum_{k \geq 1} p_{k}^{(k)} \leq \sum_{r \geq 0} k_0 p_{ir_0} r_0 \sum_{r \geq 0} (1 - p)^r < \infty.
\]

By Theorem 1.4, \( i \) is thus transient.

(ii) Denote \( C = C_1 \cup \cdots \cup C_m \). Since for any \( j \in Y \) the set \( \{ l \in S \mid j \rightarrow l \} \) is closed, it must intersect \( C \); thus for any \( j \in T \) there is some \( k \geq 1 \) such that

\[
P_{ij}^{(k)} = \sum_{l \in C} p_{jl}^{(k)} > 0.
\]

Since \( T \) is finite, we may find a \( k_0 \geq 1 \) such that for any \( j \in T \), \( p_{j}^{(k_0)} = p > 0 \). Then one may easily compute that for any \( i \in T \),

\[
P_{IT}^{(k_0)} \leq 1 - p, P_{IT}^{(2k_0)} \leq (1 - p)^2, P_{IT}^{(3k_0)} \leq (1 - p)^3, \text{ etc.}
\]

and so

\[
\sum_{k \geq 1} P_{IT}^{k} \leq \sum_{k \geq 1} k_0 p_{r_0} \sum_{r \geq 0} (1 - p)^r < \infty.
\]

By Theorem 1.4, \( i \) is thus transient. \( \square \)

1.2 Existence and Uniqueness of Stationary Distribution

A matrix \( A \in \mathbb{R}^{n \times n} \) is
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(i) nonnegative, denoted \( A \geq 0 \), if \( a_{ij} \geq 0 \ \forall \ i, j \)

(ii) positive, denoted \( A \gtrsim 0 \), if \( a_{ij} \geq 0 \ \forall \ i, j \) and \( a_{ij} > 0 \) for at least one \( i, j \)

(iii) strictly positive, denoted \( A > 0 \), if \( a_{ij} > 0 \ \forall \ i, j \)

We denote also \( A \geq B \) if \( A - B \geq 0 \), etc.

Lemma 1.6 Let \( P \geq 0 \) be the transition matrix of some regular finite Markov chain with state set \( S \). Then for some \( t_0 \geq 1 \) it is the case that \( P^t > 0 \ \forall \ t \geq t_0 \).

Proof. Choose some \( i \in S \) and consider the set

\( N_i = \{ t \geq 1 \mid p_{ii}^{(t)} > 0 \} \).

Since the chain is (finite and) aperiodic, there is some finite set of numbers \( t_1, \ldots, t_m \in N_i \) such that

\( \gcd N_i = \gcd \{ t_1, \ldots, t_m \} = 1 \),

i.e. for some set of coefficients \( a_1, \ldots, a_m \in \mathbb{Z} \),

\( a_1 t_1 + a_2 t_2 + \cdots + a_m t_m = 1 \).

Let \( P \) and \( N \) be the absolute values of the positive and negative parts of this sum, respectively. Thus \( P - N = 1 \). Let \( T \geq N(N - 1) \) and consider any \( s \geq T \). Then \( s = aN + r \), where \( 0 \leq r \leq N - 1 \) and, consequently, \( a \geq N - 1 \). But then \( s = aN + r(P - N) = (a - r)N + P \) where \( a - r \geq 0 \), i.e. \( S \) can be represented in terms of \( t_1, \ldots, t_m \) with nonnegative coefficients \( b_1, \ldots, b_m \). Thus

\( p_{ii}^{(s)} \geq p_{ii}^{(b_1 t_1)} p_{ii}^{(b_2 t_2)} \cdots p_{ii}^{(b_m t_m)} > 0 \).

Since the chain is irreducible, the claim follows by choosing \( t_0 \) sufficiently larger than \( T \) to allow all states to communicate with \( i \). \( \square \)

Let then \( A \geq 0 \) be an arbitrary nonnegative \( n \times n \)-matrix. Consider the set

\( \Lambda = \{ \lambda \in \mathbb{R} \mid Ax \geq \lambda x \text{ for some } x \geq 0 \} \).

Clearly \( 0 \in \Lambda \), so \( \Lambda \neq \emptyset \). Also, denoting

\( M = \max_i \sum_j a_{ij}, \quad x_{\text{max}} = \max_j x_j \)

it is always the case that \( Ax \leq (Mx_{\text{max}}, \ldots, Mx_{\text{max}}) \), so that if \( \lambda > M \) there cannot be any \( x \geq 0 \) such that \( Ax \geq \lambda x \). Thus \( \Lambda \subseteq [0, M] \), and we may define

\( \lambda_0 = \sup \Lambda = \max \Lambda \) \quad (by continuity).

Note that \( 0 \leq \lambda_0 \leq M \).
Theorem 1.7 (Perron-Frobenius) For any strictly positive matrix $A > 0$ there exist $\lambda_0 > 0$ and $x_0 > 0$ such that

(i) $Ax_0 = \lambda_0 x_0$;

(ii) if $\lambda \neq \lambda_0$ is any other eigenvalue of $A$, then $|\lambda| < \lambda_0$;

(iii) $\lambda_0$ has geometric and algebraic multiplicity 1.

Proof. Define $\lambda_0$ as above, and let $x_0 \geq 0$ be a vector such that $Ax_0 \geq \lambda_0 x_0$. Since $A > 0$, also $\lambda_0 > 0$.

(i) Suppose that it is not the case that $Ax_0 = \lambda_0 x_0$, i.e. that $Ax_0 \nsim \lambda_0 x_0$, but not $Ax_0 = \lambda_0 x_0$. Consider the vector $y_0 = Ax_0$. Since $A > 0$, $\lambda_0 > 0$. Consequently, $Ax_0 = \lambda_0 x_0$, and furthermore $x_0 = \frac{1}{\lambda} Ax_0 > 0$.

(ii) Let $\lambda \neq \lambda_0$ be an eigenvalue of $A$ and $y \neq 0$ the corresponding eigenvector, $Ay = \lambda y$. (Note that in general $\lambda \in \mathbb{C}$.) Denote $|y| = (|y_1|, \ldots, |y_n|)$. Since $A > 0$, it is the case that

$$A|y| \geq |Ay| = |\lambda y| = |\lambda||y|.$$

By the definition of $\lambda_0$, it follows that $|\lambda| \leq \lambda_0$.

To prove strict inequality, let $\delta > 0$ be so small that the matrix $A_\delta = A - \delta I$ is still strictly positive. Then $A_\delta$ has eigenvalues $\lambda_0 - \delta$ and $\lambda - \delta$, since

$$A_\delta = A - \delta I = (\lambda_0 - \delta) I - \lambda I.$$

Furthermore, since $A_\delta > 0$, its largest eigenvalue is $\lambda_0 - \delta$, so $|\lambda - \delta| \leq \lambda_0 - \delta$.

This implies that $A$ can have no eigenvalues $\lambda \neq \lambda_0$ on the circle $|\lambda| = \lambda_0$, because such would have $|\lambda - \delta| > |\lambda_0 - \delta|$. (See Figure 5.)

(iii) We shall consider only the geometric multiplicity. Suppose there was another (real) eigenvector $y > 0$, linearly independent of $x_0$, associated to $\lambda_0$. Then one could form a linear combination $w = x_0 + \alpha y$ such that $w \geq 0$, but not $w > 0$. However, since $A > 0$, it must be the case that also $w = \frac{1}{\lambda} Aw > 0$. □

Corollary 1.8 If $A$ is a nonnegative matrix ($A \geq 0$) such that some power of $A$ is strictly positive ($A^n > 0$), then the conclusions of Theorem 1.7 hold also for $A$. □


**Figure 5:** Maximality of the Perron-Frobenius eigenvalue.

**Proposition 1.9** Let \( A > 0 \) be a strictly positive \( n \times n \) matrix with row- and column sums

\[
\begin{align*}
  r_i &= \sum_j a_{ij}, & c_j &= \sum_i a_{ij}, & i, j = 1, \ldots, n
\end{align*}
\]

Then for the “Perron-Frobenius eigenvalue” \( \lambda_0 \) of Theorem 1.7 the following bounds hold:

\[
\min_i r_i \leq \lambda_0 \leq \max_i r_i, \quad \min_j c_j \leq \lambda_0 \leq \max_j c_j.
\]

**Proof.** Let \( x_0 = (x_1, x_2, \ldots, x_n) \) be an eigenvector corresponding to \( \lambda_0 \), normalised so that \( \sum_i x_i = 1 \). Summing up the equations for \( Ax_0 = \lambda_0 x_0 \) yields:

\[
\begin{align*}
  a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n &= \lambda_0 x_1 \\
  a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n &= \lambda_0 x_2 \\
  \vdots \\
  c_1x_1 + c_2x_2 + \ldots + c_nx_n &= \lambda_0 (x_1 + \cdots + x_n) = \lambda_0
\end{align*}
\]

Thus \( \lambda_0 \) is a “weighted average” of the column sums, so in particular \( \min_j c_j \leq \lambda_0 \leq \max_j c_j \).
Applying the same argument to $A^T$, which has the same $\lambda_0$ as $A$, yields the row sum bounds. □

**Corollary 1.10** Let $P \geq 0$ be the transition matrix of a regular Markov chain. Then there exists a unique distribution vector $\pi$ such that $\pi P = \pi$. ($\Leftrightarrow P^T \pi^T = \pi^T$)

*Proof.* By Lemma 1.6 and Corollary 1.8, $P$ has a unique largest eigenvalue $\lambda_0 \in \mathbb{R}$. By Proposition 1.9, $\lambda_0 = 1$, because as a stochastic matrix all row sums of $P$ (i.e. the column sums of $P^T$) are 1. Since the geometric multiplicity of $\lambda_0$ is 1, there is a unique stochastic vector $\pi$ (i.e. satisfying $\sum_i \pi_i = 1$) such that $\pi P = \pi$. □

1.3 Convergence of Regular Markov Chains

In Corollary 1.10 we established that a regular Markov chain with transition matrix $P$ has a unique stationary distribution vector $\pi$ such that $\pi P = \pi$.

By elementary arguments (page 2) we know that starting from any initial distribution $q$, if the iteration $q, qP, qP^2, \ldots$ converges, then it must converge to this unique stationary distribution.

However, it remains to be shown that if the Markov chain determined by $P$ is regular, then the iteration always converges.

The following matrix decomposition is well known:

**Lemma 1.11** (Jordan canonical form) Let $A \in \mathbb{C}^{n \times n}$ be any matrix with eigenvalues $\lambda_1, \ldots, \lambda_l \in \mathbb{C}$, $l \leq n$. Then there exists an invertible matrix $U \in \mathbb{C}^{n \times n}$ such that

$$U A U^{-1} = \begin{bmatrix} J_1 & 0 & \cdots & 0 \\ 0 & J_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & J_r \end{bmatrix}$$

where each $J_i$ is a $k_i \times k_i$ Jordan block associated to some eigenvalue $\lambda$ of $A$:

$$J_i = \begin{bmatrix} \lambda & 1 & 0 & \cdots & 0 & 0 \\ 0 & \lambda & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda & 1 \\ 0 & 0 & 0 & \cdots & 0 & \lambda \end{bmatrix}$$