

# Proof Theoretical Framework and Term Equations

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pp. 82 – 103 from the Apt's book.

## From the previous lectures

- Equivalence of CSPs
- Constraint solvers
  - Complete constraint solver
  - Incomplete constraint solver

## A proof theoretical framework

- Used to define complete constraint solvers
- Proof rules (equivalence preserving)
  - Domain reduction rules
  - Transformation rules

## Proof rules

Let us assume that  $\phi$  and  $\psi$  are CSPs. A proof rule

$$\frac{\phi}{\psi} \text{ or } \frac{\langle \mathcal{C}; \mathcal{DE} \rangle}{\langle \mathcal{C}'; \mathcal{DE}' \rangle}$$

- is equivalence preserving if  $\phi$  and  $\psi$  are equivalent.
- is consistency preserving if  $\phi$  and  $\psi$  are both either consistent or inconsistent

## Domain reduction rules

Assume that  $\phi := \langle \mathcal{C}; \mathcal{D}\mathcal{E} \rangle$  and  $\psi := \langle \mathcal{C}'; \mathcal{D}\mathcal{E}' \rangle$

- $\mathcal{D}\mathcal{E} := x_1 \in D_1, \dots, x_n \in D_n$
- $\mathcal{D}\mathcal{E}' := x_1 \in D'_1, \dots, x_n \in D'_n$
- $\forall i \in [1, n] : D'_i \subseteq D_i$
- $\mathcal{C}'$  is obtained from  $\mathcal{C}$  by restricting each constraint to the corresponding subsequence of the domains  $D'_1, \dots, D'_n$
- failure as empty set

## Domain reduction rules

### Linear Disequality:

Our old friend who deals with linear inequalities over **integer** intervals:

$$\frac{\langle x < y; x \in [l_x, h_x], y \in [l_y, h_y] \rangle}{\langle x < y; x \in [l_x, \min(h_x, h_y - 1)], y \in [\max(l_y, l_x + 1), h_y] \rangle}$$

## Domain reduction rules

### Equality:

$$\frac{\langle x=y; x \in D_x, y \in D_y \rangle}{\langle x=y; x \in D_x \cap D_y, y \in D_x \cap D_y \rangle}$$

- The constraint is solved if
  - $D_x \cap D_y = \emptyset$
  - $D_x \cap D_y$  is a singleton set

## Domain reduction rules

### Disequality:

$$\frac{\langle x \neq y; x \in D_x, y = a \rangle}{\langle ; x \in D - a, y = a \rangle}$$

- Failure if  $D_x - \{a\} = \emptyset$

## Transformation rules

- $\frac{\langle \mathcal{C}; \mathcal{DE} \rangle}{\langle \mathcal{C}'; \mathcal{DE}' \rangle}$
- $\mathcal{C}' \neq \emptyset$
- $\mathcal{DE}'$  extends  $\mathcal{DE}$
- failure when  $\perp$  generated

## Transformation rules

### Disequality transformation:

$$\frac{\langle s \neq t; \mathcal{DE} \rangle}{\langle x \neq t, x = s'; \mathcal{DE}', x \in \mathcal{Z} \rangle}$$

- $s$  is not a variable
- $\mathcal{DE}$  includes all the variables of  $s$  and  $t$
- $x$  doesn't appear in  $\mathcal{DE}$

## Transformation rules

### Variable elimination:

$$\frac{\langle \mathcal{C}; \mathcal{DE}, x=a \rangle}{\langle \mathcal{C}\{x/\bar{a}\}; \mathcal{DE}', x=a \rangle}$$

- $\{x/\bar{a}\}$  is a substitution
- $\bar{a}$  stands for the constant that denotes the value of  $a$  in our language of constraints

### Example:

$$\frac{\langle 3xy^2 + 5xy - 5yz \leq 6; x \in [0,100], y=2, z \in [0,100] \rangle}{\langle 3 \cdot x \cdot 4 + 5 \cdot x \cdot 2 - 5 \cdot 2 \cdot z \leq 6, x \in [0,100], y=2, z \in [0,100] \rangle}$$

## Transformation rules

### Resolution:

$$\frac{\langle C_1 \vee L, C_2 \vee \bar{L} \rangle}{\langle C_1 \vee L, C_2 \vee \bar{L}, C_1 \vee C_2 \rangle}$$

### Introduction rules in general:

$$\frac{\langle \mathcal{C}; \mathcal{DE}, \rangle}{\langle \mathcal{C}, C; \mathcal{DE}, x=a \rangle}$$

- new constraint  $C$  is introduced

## Applying rules

Let  $\mathcal{P} = \langle \mathcal{C} \cup \mathcal{C}_1; \mathcal{DE}, \mathcal{DE}_1 \rangle$  be a CSP and  $\frac{\langle \mathcal{C}_1; \mathcal{DE}_1, \rangle}{\langle \mathcal{C}_2; \mathcal{DE}_2 \rangle}$  rule ( $R$ ) that we are trying to apply on  $\mathcal{P}$ .

- Variable that appears in the conclusion but not in the premise is called *introduced variable*  
Application of the  $R$  to the CSP  $\mathcal{P}$ :
- $R$  is applied on  $\mathcal{P}$ 
  1. **renaming** introduced variables
  2. **replacing**  $\langle \mathcal{C}_1; \mathcal{DE}_1, \rangle$  with  $\langle \mathcal{C}_2; \mathcal{DE}_2 \rangle$
  3. **restricting** the constraint of  $\mathcal{C}$  to the domains of  $\mathcal{DE}, \mathcal{DE}_2$

## Applying rules

- When **equivalence preserving rule ( $R$ )** is applied on  $\phi$  to get  $\psi$ ,  $\phi$  and  $\psi$  are equivalent
- if  $\phi$  differs from  $\psi$ , the application of  $R$  was **relevant**
- CSP  $\phi$  is **closed under the application of  $R$**  if one of the following holds:
  - $R$  cannot be applied to  $\phi$
  - application of  $R$  is not relevant

## Derivations

**Derivation** is a sequence of CSPs obtained by applying the proof rules. A finite derivation is called:

- **successful** if the last CSP is the first solved CSP
- **failed** if last CSP is the first failed CSP
- **stabilising** if the last CSP is closed under the rules

## Term equation

**Alphabet** consists of

- fixed and infinite set of **variables**
- set of **functions**, each function has a fixed arity (possibly zero)
- “(”, “)” and “,”

**Terms** are defined recursively

- a variable is a term
- a function that is applied on terms is a term

## Substitution

Finite mapping from variables to terms

$$\{x_1/t_1, \dots, x_n/t_n\}$$

- variables:  $x_1, \dots, x_n$  –

$$Dom(\theta) = \{x_1, \dots, x_n\}$$

- terms:  $t_1, \dots, t_n$  –  $Range(\theta) = \{t_1, \dots, t_n\}$

- binding:  $x_i/t_i$

- $\forall i \in [1, n] : x_i \neq t_i$

## Substitutions

Applying substitution  $\theta$  to the term  $s$

- $s\theta$  (instance of  $s$ )
- simultaneously for each binding of  $\theta$ :
  - in the term  $s$ , replace variable  $x_i$  with term  $t_i$

**Example:** language of arithmetic expressions

$$((1 + x) + y - 1)\{x/y\} \equiv ((1 + y) + y - 1)$$

## Composite substitutions

Let  $\theta$  and  $\eta$  be substitutions. **Composition** of  $\theta$  and  $\eta$ :

$$(\theta\eta)(x) := (x\theta)\eta$$

$\theta$  is **more general than**  $\tau$  if for some substitution  $\eta$

$$\tau = \theta\eta$$

e.g.  $\theta := \{y/g(x, a), z/b\}$ ,  $\tau := \{x/c, y/g(c/a), z/b\}$

## Unification

- $\theta$  **unifies**  $s$  and  $t$  iff  $s\theta \equiv t\theta$
- $\theta$  is a **mgu** of  $s$  and  $t$  iff
  1.  $s\theta \equiv t\theta$
  2.  $\theta$  is more general than all unifiers of  $s$  and  $t$

**Example:**  $\{y/g(x,a), z/b\}$  is an mgu of  $f(g(x, a), z)$  and  $f(y, b)$

## Unification

- $\theta$  is a unifier of  $E := \{s_1 = t_1, \dots, s_n = t_n\}$   
if

$$s_1\theta \equiv t_1\theta, \dots, s_n\theta \equiv t_n\theta$$

### Solved form:

$E$  is in solved form iff

$\forall i \in [1, n] : x_i \notin Var(t_i)$  and  $x_i$  is not elsewhere in  $E$  than on the left hand side of the  $x_i = t_i$

## Strong mgu

Call an mgu  $\theta$  of a set of equations  $E$  **strong** if for every unifier  $\eta$  of  $E$  we have  $\eta = \theta\eta$ .

**Lemma:** If  $E := \{s_1 = t_1, \dots, s_n = t_n\}$  is in **solved form** then  $\theta := \{s_1/t_1, \dots, s_n/t_n\}$  is a **strong mgu**.

## Unif. prob. as CSP

- $\tau$  set of all terms
- $s = t \mapsto \{(x_1\eta, \dots, x_n\eta) | \eta \text{ unifies } s \text{ and } t\}$

**Example:**  $x = f(y)$

## UNIF proof system...

### Decomposition

$$\frac{f(s_1, \dots, s_n) = f(t_1, \dots, t_n)}{s_1 = t_1, \dots, s_n = t_n}$$

### Failure 1

$$\frac{f(s_1, \dots, s_n) = g(t_1, \dots, t_n)}{\perp}, f \not\equiv g$$

### Deletion

$$\underline{x=x}$$

## ... UNIF proof system

### Transposition

$$\frac{t=x}{x=t}, \text{ } t \text{ is not a variable}$$

### Substitution

$$\frac{x=t, E}{x=t, E\{x/t\}}, \text{ } x \notin Var(t) \wedge x \in Var(E)$$

### Failure 2

$$\frac{x=t}{\perp}, \text{ where } x \in Var(t) \text{ and } x \not\equiv t$$

## Example



**Theorem** Consider a failed or a stabilising derivation in the UNIF system, starting eith a finite set of equtions  $E$  and terminating with a set of constraints  $F$ . If  $E$  has a unifier then  $F$  is a solved form that determines an mgu of  $E$  . If there is no unifier for  $E$  then  $F$  contains  $\perp$ .

## Summary

- domain reduction—*vs.* transformation rules
- term equation
- substitution and mgu
- unification problems and CSP
- *UNIF* system
- applications?

## kotitehtävä 1

Esitä jokin kokonaislukudomaineihin ja rajoitteisiin perustuva CSP, jolla on

- a) Stabiloituva, epäonnistuva johto, jonka pituus on vähintään 4 askelta
- b) Onnistunut johto, jonka pituus on vähintään 4 askelta
- c) Äärettömän pituinen johto

Esitä jokaisesta kohdasta käyttämäsi säätöjoukko (Esimerkiksi esityksen alussa olleet muokkaussäännöt domainia pienentävät säännöt ovat sopiva joukko kaikkiin kohtiin), CSP ja pyydetty johto sille (c- kohdassa riittää, että esität, miten johto konstruoidaan). Jokaisessa johdossa on käytettävä vähintään kahta eri säätöä.

Johdossa saa käyttää peruskoulusta tuttua aritmetiikkaa Älä palauta kirjan esimerkkejä.

## kotitehtävä 2

- a) Olkoon  $E := \{f(g(x, a), z) = f(y, b)\}$ . Etsi  $E$ :n mgu, jos sellainen on olemassa käyttäen UNIF säätöjoukkoa. Jos unifioijaa ei ole olemassa, niin todista se.
- b) Olkoon

- $t_1 = f_2(f_1(g(x, a)), x)$
- $t_2 = f_2(f_1(y), b)$

Etsi termien  $t_1$  ja  $t_2$  mgu, jos sellainen on olemassa käyttäen UNIF säätöjoukkoa. Jos unifioijaa ei ole olemassa, niin todista se.