BE-BB(k)

# Motivation (1/2)

- Most CSP solvers apply
  - search or
  - dynamic programming.
- Search:
  - Branch-and-bound (BB) in constraint optimization
  - Relation propagation in constraint satisfaction
  - Worst-case: explore whole search tree; exponential in n
- Dynamic programming:
  - Sequence of transformation reduce problem size
  - Bucket elimination (BE): basic step variable elimination
  - Worst-case exponential in arity of induced constraints

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#### Motivation (2/2)

- Idea: Combine BB and  $\mathsf{BE} \to \mathsf{get}$  best out of both worlds?
  - Apply variable elimination if induces constraints are of low arity
  - Controlled by parameter  $\boldsymbol{k}$
  - Else switch to search
- Solution BE-BB(k)
  - worst-case time/space exponential in k
- Properties:
  - May boost search in constraint satisfaction, no worsening effect
  - Overwhelming advantage on some optimization tasks

#### Outline

**BE-BB(***k***)**:

A Hybrid Method for Solving CSPs and COPs

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Based on J. Larrosa and R. Dechter. Boosting Search with Variable

Elimination in Constraint Optimization and Constraint Satisfaction

Problems. To appear in Constraint Journal.

- Motivation
- CSPs and COPs
- Branch-and-Bound (BB)
- Bucket elimination (BE)
- Combining BE and BB: BE-BB(k)

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#### **CSPs** Revisited

#### Constraint satisfaction problem (CSP):

- $X = \{x_1, \ldots, x_n\}$ : set of *variables*
- $D = \{D_1, \dots, D_n\}$ : set of *domains*, where  $x_i \in D_i$
- $C = \{R_1, \ldots, R_m\}$ : set of *constraints*, where  $R \in C$  is a *relation* over the *scope*  $var(R) \subseteq X$
- Solution: assignment of values for each  $x_i \in X$  from  $D_i$  s.t. constraints in C are satisfied
- Arity of a constraint R is |var(R)|
- Arity of a CSP:  $\max_{R \in C} \{ |var(R)| \}$

#### **Branch-and-Bound Revisited**

A *search schema* for COP solving:

- Traverses the search tree defined by the problem
- Internal nodes: incomplete assignments
- Leaf nodes: complete assignments (optimal or not)
- Upkeeps *upper* (UB) and *lower bounds* (LB) for the best possible solution
  - If  $UB \leq LB(t)$  for a partial assignment t, *backtrack*
- Basic step: *branching*

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## **COPs** Revisited

*Constraint optimization problem* (COP): a CSP with two types of constraints

- *Hard constraints* (as in a CSP)
- Soft constraints (denoting preferences among tuples
- Constraints are seen as *cost functions* 
  - Returns for each tuple a non-negative cost
  - Hard constraints assign cost  $0/\infty$  to allowed/forbidden tuples
- *Weighted* CSP (WCSP):

Minimize the objective function:the sum of all constraints  $C = \{f_1, \ldots, f_m\}$ 

$$f^*(X) = \sum_{j=1}^m f_j$$

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## **Lower Bound Computation**

$$LB(t) = \sum_{f \in C} \min_{q} \{f(t,q)\},\$$

where

- t: the current partial assignment,
- min<sub>q</sub>{f(t,q)}: minimum cost extension of t to variables in var(f) not assigned in t
- Time complexity:  $\mathcal{O}(m \cdot d^{r-1})$
- Reduce to  $\mathcal{O}(m \cdot d^s)$  by considering only constraints f having at most s uninstantiated variables in var(f)

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# BE-BB(k)

Worst-case comparison:

	time	space
BB	exp in $n$	linear (in $n$ )
BE	exp in arity of $f_i$ , linear in $n$	exp in arity of $f_i$ , linear in $n$

• Note: Determining the best ordering (w.r.t.  $f_i$ s) is **NP**-complete

BE-BB(k): The following recursive idea

- Eliminate  $x_i$ s s.t. the arity of  $f_i$  is  $\leq k$  with BE
- Then apply BB to the reduced problem: branch on a variable, then apply BE again if possible

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## Bucket Elimination (2/2)

**Bucket Elimination** 

•  $B_i$  constains such constraints f in which  $x_i$  is the highest one in

• *Eliminates variables* one-by-one in descending order according to o

• Summarizes the effect by generating an additional constraint

A dynamic programming schema for solving COPs

• A variable ordering *o* is assumed

• Partitions C into buckets  $B_i$ 

var(f) according to o

• The additional constraint:

$$\operatorname{elim}_i(\sum_{f\in B_i} f),$$

where

- (f+g)(X) = f(X) + g(X) with scope  $var(f) \cup var(g)$ , and
- $(\operatorname{elim}(f)_i)(X) = \min_{a \in D_i} \{f(X[x_i = a])\}$  with scope  $var(f) \{x_i\}$
- Last elimination produces a constant function having the value of the optimal cost
- The optimal assignment can then be generated *backtrack-free*: Value for  $x_i$ : best extension of  $(x_1, \ldots, x_{i-1})$  relative to

 $\mathsf{BE-BB}(k)$ 

#### **Ending Remarks**

#### BE-BB(k)

- A generalization for CSP/COP solving of an idea of combining search and directed resolution in SAT solving
- Boosts branch-and-bound with bucket elimination
- A structural parameter defines when to BB/BE
- As usual, variable ordering is somewhat crucial
- "Overwhelming advantage" on some COPs reported

$$\sum_{f \in B_i} f$$