

T-79.186

Spring 2005

Reactive Systems

Home Exercise 2

Deadline 28.2 16:15

Return your answers by email to Misa.Keinanen@hut.fi.

For this home exercise round use the definition of automata as given by Chapter 1 of the book: Bérard et al: Systems and Software Verification.

- 1.) (a) Give an automata description  $\mathcal{A}_3$  (without using variables) for a modulo 3 counter, which has the following actions: (i) *dec* decreases the value of the counter by one (mod 3), and (ii) *inc2* increases the value of the counter by two (mod 3). In the initial state of the automaton the value of the counter should be 0.
- (b) Give another automaton  $\mathcal{A}_4$ , which is a modulo 4 counter, and also has the actions *dec* and *inc2*.
- (c) Compute the synchronised product automaton  $\mathcal{P} = \mathcal{A}_3 \times \mathcal{A}_4$  using the synchronisation set  $Sync = \{(dec, inc2), (inc2, dec)\}$ .
- 2) (a) In the book (Bérard et al., pages 21–23) an elevator system is described that is a synchronised product of five automata (3 doors, a cabin, and a controller). Give a partial execution of  $\mathcal{P}$ , which ends in any state where the controller is in the state **free2**.  
Note that the book has the following off-by-one errors in the definition of the set *Sync* on page 23: the numbering of the doors should be from 0 to 2 instead from 1 to 3 as in the (faulty) definition of *Sync* in the book.
- (b) Give the set of reachable states of Peterson’s MUTEX-algorithm (Bérard et al., pages 25-26).