

Representing Normal Programs with Clauses

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OUTLINE

- ① Terms and Definitions
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- ⑤ Discussion

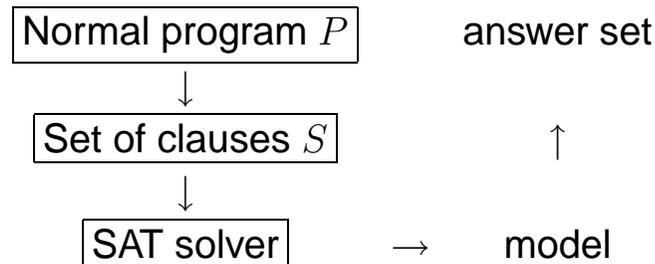


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MOTIVATION

- Our goal is to combine the knowledge representation capabilities of normal logic programs with the efficiency of SAT solvers.



- To realize this setting, we present a **polynomial** and **faithful** but **non-modular** translation.



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① TERMS AND DEFINITIONS

- A **rule** r is an expression of the form

$$h \leftarrow b_1, \dots, b_n, \sim c_1, \dots, \sim c_m.$$

- We use the following notations for a rule r :

$$\begin{aligned} H(r) &= h && \text{(head)} \\ B(r) &= \{b_1, \dots, b_n, \sim c_1, \dots, \sim c_m\} && \text{(body)} \\ B^+(r) &= \{b_1, \dots, b_n\} \\ B^-(r) &= \{c_1, \dots, c_m\} \end{aligned}$$

- We define **normal logic programs**, or **normal programs** for short, as sets of rules.



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Syntactic Restrictions

- We distinguish the following special cases:
 - **positive** rules: $h \leftarrow b_1, \dots, b_n$
 - **atomic** rules: $h \leftarrow \sim c_1, \dots, \sim c_m$
 - strictly **unary** rules: $h \leftarrow b, \sim c_1, \dots, \sim c_m$
 - strictly **binary** rules: $h \leftarrow b_1, b_2, \sim c_1, \dots, \sim c_m$
- We extend these conditions for sets of rules:
 - **positive** programs: $\forall r \in P : |B^-(r)| = 0$
 - **atomic** programs: $\forall r \in P : |B^+(r)| = 0$
 - **unary** programs: $\forall r \in P : |B^+(r)| \leq 1$
 - **binary** programs: $\forall r \in P : |B^+(r)| \leq 2$

Level Numbers

Definition: For each atom $b \in LM(P)$, the **level number** $\text{lev}(b)$ of b is the least number n such that $b \in T_P \uparrow n - T_P \uparrow (n - 1)$.

Example: Consider a positive normal program

$$P = \{r_1 = a \leftarrow; r_2 = a \leftarrow b; r_3 = b \leftarrow a\}$$

with $LM(P) = \{a, b\}$ and the corresponding level numbers $\text{lev}(a) = 1$ and $\text{lev}(b) = 2$.



Least Models

If P is a **positive** normal program, then

1. P has a unique minimal model, i.e. the **least model** $LM(P)$ of P ;
2. $LM(P) = T_P \uparrow \omega = \text{lfp}(T_P)$ where the **immediately true operator** T_P is defined by

$$T_P(A) = \{H(r) \mid r \in P \text{ and } B^+(r) \subseteq A\};$$

and

3. $\text{lfp}(T_P) = T_P \uparrow i$ for some $i \in \mathbb{N}$, if P is finite.

Stable and Supported Models

Definition: Given an interpretation M , the Gelfond-Lifschitz **reduct**

$$P^M = \{r^+ \mid r \in P \text{ and } B^-(r) \cap M = \emptyset\}$$

where r^+ is defined as $H(r) \leftarrow B^+(r)$ for $r \in P$.

Definition: For a normal program P , an interpretation $M \subseteq \text{At}(P)$ is

1. a **stable model** of $P \iff M = LM(P^M)$, and
2. a **supported model** of $P \iff M = T_{P^M}(M)$.



Stable and Supported Models

Example: The normal program

$P = \{a \leftarrow b; b \leftarrow a\}$ has two supported models
 $M_1 = \emptyset$ and $M_2 = \{a, b\}$, but only M_1 is stable, as
 $\text{LM}(P^{M_1}) = \text{LM}(P) = \emptyset = M_1$ and
 $\text{LM}(P^{M_2}) = \text{LM}(P) = \emptyset \neq M_2$.

Some important properties:

1. Stable models are also supported models.
2. Stable and supported models coincide for **atomic** programs.
3. Clark's completion captures supported models.



② CHARACTERIZING STABILITY

Definition: Let M be a supported model of a normal program P . A **level numbering** w.r.t. M is a function $\# : M \cup \text{SR}(P, M) \rightarrow \mathbb{N}$ such that

1. for all $a \in M$,
 $\#a = \min\{\#r \mid r \in \text{SR}(P, M) \text{ and } a = H(r)\}$ and
2. for all $r \in \text{SR}(P, M)$,
 $\#r = \max\{\#b \mid b \in B^+(r)\} + 1$

where $\text{SR}(P, M) = \{r \in P \mid M \models B(r)\}$.

We define $\max \emptyset = 0$ to cover rules r with $B^+(r) = \emptyset$.



Capturing Stable Models

Let M be a supported model of P .

Proposition: If $\#$ is a level numbering w.r.t. M , then it is unique.

Theorem: M is a **stable model** of P

\iff there is a level numbering $\#$ w.r.t. M .



Capturing Stable Models

Example: Recall the supported models of
 $P = \{r_1, r_2\}$ with $r_1 = a \leftarrow b$ and $r_2 = b \leftarrow a$:
 $M_1 = \emptyset$ and $M_2 = \{a, b\}$.

- Since $M_1 \cup \text{SR}(P, M_1) = \emptyset$, M_1 is trivially stable.
- For M_2 , the domain $M_2 \cup \text{SR}(P, M_2) = M_2 \cup P$ and the set of equations

$$\begin{aligned}\#a &= \#r_1, \#r_1 = \#b + 1, \\ \#b &= \#r_2, \#r_2 = \#a + 1\end{aligned}$$

has no solution. Thus M_2 is not stable.



③ CLAUSAL REPRESENTATION

- We use an **atomic normal program** $\text{Tr}_{\text{AT}}(P) =$

$$\text{Tr}_{\text{SUPP}}(P) \cup \text{Tr}_{\text{CTR}}(P) \cup \text{Tr}_{\text{MIN}}(P) \cup \text{Tr}_{\text{MAX}}(P)$$

as an intermediary representation when translating a normal program P into a set of clauses $\text{Tr}_{\text{CL}}(\text{Tr}_{\text{AT}}(P))$.

- Level numbers have to be captured using **binary counters** which are represented by vectors of propositional atoms.
- Certain primitives have to be represented: $\text{SEL}(c)$, $\text{NXT}(c, d)$, $\text{FIX}(c)$, $\text{LT}(c, d)$, $\text{EQ}(c, d)$.



Example

For $P = \{a \leftarrow b; b \leftarrow a\}$, the translation $\text{Tr}_{\text{AT}}(P)$ contains the following rules for a :

$$b \leftarrow \sim \overline{\text{bt}(r_2)}; \overline{\text{bt}(r_2)} \leftarrow \sim \text{bt}(r_2); \text{bt}(r_2) \leftarrow \sim \bar{a};$$

$$\bar{a} \leftarrow \sim a; x \leftarrow \sim x, \sim \bar{a}, \sim \min(a);$$

$$x \leftarrow \sim x, \sim \overline{\text{bt}(r_2)}, \sim \overline{\text{lt}(\text{nxt}(a), \text{ctr}(b))_1}; \text{ and}$$

$$\min(b) \leftarrow \sim \overline{\text{bt}(r_2)}, \sim \overline{\text{eq}(\text{nxt}(a), \text{ctr}(b))}$$

in addition to four subprograms for choosing the values of $\text{ctr}(a)$ and $\text{nxt}(a)$ as well as comparing the latter with $\text{ctr}(b)$. The rules for b are symmetric.

The only stable model is $N = \{\bar{a}, \bar{b}, \overline{\text{bt}(r_1)}, \overline{\text{bt}(r_2)}\}$.



Optimizations

- The level numbers associated with rules can be totally omitted, if all **non-binary** rules r with $|\text{B}^+(r)| > 2$ are translated away.
- A normal logic program P is partitioned into its **strongly connected components** C_1, \dots, C_n on the basis of positive dependencies.
- No counters are needed, if $|\text{H}(C_i)| = 1$ holds.
- The number of bits $\nabla C_i = \lceil \log_2(|\text{H}(C_i)| + 2) \rceil$ for other strongly connected components C_i .
- Fixed translation schemes can be devised for atomic, strictly unary, and strictly binary rules.



④ EXPERIMENTS

- We have implemented Tr_{AT} and Tr_{CL} as respective translators LP2ATOMIC and LP2SAT to be used together with LPARSE.
- Our experiments were run on a 1.67 GHz CPU with 1GB memory.
- In our benchmark, we compute all subgraphs of D_n whose all vertices are mutually reachable.

Here D_n is a directed graph with n vertices and $n^2 - n$ edges: $E_n = \{\langle i, j \rangle \mid 0 < i \leq n, 0 < j \leq n, i \neq j\}$.



Reachability Benchmark

```

vertex(1..n).
in(V1,V2) :- not out(V1,V2),
             vertex(V1;V2), V1!=V2.
out(V1,V2) :- not in(V1,V2),
             vertex(V1;V2), V1!=V2.
reach(V,V) :- vertex(V).
reach(V1,V3) :- in(V1,V2), reach(V2,V3),
               vertex(V1;V2;V3), V1!=V2, V1!=V3.
:- not reach(V1,V2), vertex(V1;V2).
    
```

☞ The order in which the reachability of nodes inferred cannot be determined beforehand.

Computing Only One Solution

Number of Vertices	8	9	10
S MODELS	0.009	0.013	0.022
C MODELS	0.046	0.042	0.055
LP2ATOMIC+S MODELS	>10 ⁴	>10 ⁴	>10 ⁴
LP2SAT+CHAFF	0.771	32.6	254
LP2SAT+RELSAT	2.51	>10 ⁴	>10 ⁴
WF+LP2SAT+RELSAT	2.80	4830	>10 ⁴
ASSAT	0.023	0.028	0.037

Computing All Solutions

Number of Vertices	1	2	3	4	5
S MODELS	0.004	0.003	0.003	0.033	12
C MODELS	0.031	0.030	0.124	293	-
LP2ATOMIC+S MODELS	0.004	0.008	0.013	0.393	353
LP2SAT+CHAFF	0.011	0.009	0.023	1.670	-
LP2SAT+RELSAT	0.004	0.005	0.018	0.657	1879
WF+LP2SAT+RELSAT	0.009	0.013	0.018	0.562	1598
Models	1	1	18	1606	565080
SCCs with H(C) > 1	0	0	3	4	5
Rules (LPARSE)	3	14	39	84	155
Rules (LP2ATOMIC)	3	18	240	664	1920
Clauses (LP2SAT)	4	36	818	2386	7642
Clauses (WF+LP2SAT)	2	10	553	1677	5971

⑤ DISCUSSION

- The new characterization of stable models is based on **canonical** level numberings.
- The translation function $\text{Tr}_{\text{AT}} \circ \text{Tr}_{\text{CL}}$ has distinctive properties:
 - it covers all finite normal programs P ,
 - a bijective relationship of models is obtained
 - the Herbrand base $\text{At}(P)$ is preserved,
 - the length $\|\text{Tr}_{\text{CL}}(\text{Tr}_{\text{AT}}(P))\|$ is of order $\|P\| \times \log_2 |\text{At}(P)|$, and
 - incremental updating is not needed.

Conclusions and Future Work

- Various kinds of closures of relations, such as **transitive closure**, can be properly captured with classical models.
- Our approach is competitive against other SAT-solver-based approaches when the task is to compute all stable models.
- Further optimizations should be pursued for in order to really compete with SMOBELS.
- In the future, we intend to study techniques to reduce the number of binary counters and the numbers of bits involved in them.

